

Plan

- 1 Matrices and determinants
- 2 Minors and rank
- 3 Solving linear systems using minors

$m \times n$ matrix $A = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{pmatrix}$

A is square if $m=n$

① Determinants

A $n \times n$ matrix $\rightarrow \det(A) = |A|$
determinant of A , a number

Ex:

$A = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 4 \\ 1 & 3 & 9 \end{pmatrix}$

$\begin{vmatrix} 1 & 1 & 1 \\ 1 & 2 & 4 \\ 1 & 3 & 9 \end{vmatrix}$

$= +1 \cdot \begin{vmatrix} 2 & 4 \\ 3 & 9 \end{vmatrix} - 1 \cdot \begin{vmatrix} 1 & 4 \\ 1 & 9 \end{vmatrix} + 1 \cdot \begin{vmatrix} 1 & 2 \\ 1 & 3 \end{vmatrix}$
 $= 6 - 5 + 1 = \underline{\underline{2}}$

Sign: $\begin{pmatrix} + & - & + \\ - & + & - \\ + & - & + \end{pmatrix}$

minor: $M_{ij} = \det.$ of the matrix you get when you delete row i , col j

$C_{ij} = (-1)^{i+j} \cdot M_{ij}$

Fact: Cofactor expansion along any row or column of A gives $\det(A)$.

Review Lecture 2

- Solve vector eqn. using Gaussian elim.
- span and linear independence of vectors
- dimension and base of vector spaces, examples of vector spaces are column/null space of a matrix

Methods for computing $\det(A)$

- ① Cofactor expansion
- ② Using Gaussian process

Ex: $\begin{vmatrix} 1 & 1 & 1 \\ 1 & 2 & 4 \\ 1 & 3 & 9 \end{vmatrix} \begin{matrix} \leftarrow -1 \\ \leftarrow -1 \end{matrix} = \begin{vmatrix} 1 & 1 & 1 \\ 0 & 1 & 3 \\ 0 & 2 & 8 \end{vmatrix} \begin{matrix} \leftarrow -2 \end{matrix}$

$+1 \cdot \begin{vmatrix} 1 & 1 \\ 0 & 2 \end{vmatrix} = +1 \cdot 1 \cdot 2$
 $\begin{vmatrix} 1 & 1 & 1 \\ 0 & 1 & 3 \\ 0 & 0 & 2 \end{vmatrix}$
 $= 1 \cdot 1 \cdot 2 = \underline{\underline{2}}$

Fact: $A \rightarrow B$ are elementary row operation.

- i) $|B| = -|A|$ if we switch two rows
- ii) $|B| = c \cdot |A|$ if we multiply a row by c
- iii) $|B| = |A|$ if we add a multiple of one row to another row

Fact:
 The determinant of an upper triangular matrix is the product of the diagonal entries

Notice: i) You can only compute determinants of square matrices
 ii) Square echelon forms are always upper triangular

upper triangular:
 all entries under the main diagonal are zero

Ex:

$$\begin{vmatrix} 1 & 2 & 1 & 0 \\ 0 & 3 & 4 & 7 \\ 0 & 0 & 3 & 1 \\ 0 & 0 & 0 & 4 \end{vmatrix}$$

echelon form
 $\det = 1 \cdot 3 \cdot 3 \cdot 4$
 $= \underline{\underline{36}} \neq 0$

$$\begin{vmatrix} 1 & 2 & 1 & 0 \\ 0 & 3 & 4 & 7 \\ 0 & 0 & 2 & 1 \\ 0 & 0 & 0 & 0 \end{vmatrix}$$

echelon form
 $\det = 0$

$$\begin{vmatrix} 1 & 2 & 3 & 4 \\ 0 & 0 & 7 & 1 \\ 0 & 0 & 0 & 3 \\ 0 & 0 & 0 & 0 \end{vmatrix}$$

$|A| \neq 0$ $|A| = 0$ A $n \times n$
matrix

- | | |
|---|--|
| <ul style="list-style-type: none"> * $\text{rk } A = n$ * $A\underline{x} = \underline{b}$ has a unique solution for every \underline{b} * A is invertible
($A^{-1} = \frac{1}{ A } \cdot \text{adj}(A)$) * the rows of A are linearly independent * the cols of A are linearly independent | <ul style="list-style-type: none"> * $\text{rk } A < n$ * $A\underline{x} = \underline{b}$ has either no solutions or inf. many solutions for any \underline{b}. * A is not invertible (there is no inverse) * the rows of A are linearly dependent * the cols of A are linearly dependent |
|---|--|

Recall: - any linear system with augmented matrix $(A|\underline{b})$ can be written $A\underline{x} = \underline{b}$, with $\underline{x} = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}$.

- An inverse A^{-1} of A is a matrix

such that $\begin{cases} A \cdot A^{-1} = I \\ A^{-1} \cdot A = I \end{cases}$ where $I = \begin{pmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 1 \end{pmatrix}$
identity matrix

and $A^{-1} = \frac{1}{|A|} \cdot \begin{pmatrix} c_{11} & \dots & c_{1n} \\ \vdots & \ddots & \vdots \\ c_{n1} & \dots & c_{nn} \end{pmatrix}^T$

- useful formulas:

$$\begin{array}{llll} \text{i) } |A \cdot B| & \text{ii) } |A^T| & \text{iii) } (AB)^{-1} & \text{iv) } (AB)^T \\ = |A| \cdot |B| & = |A| & = B^{-1} \cdot A^{-1} & = B^T \cdot A^T \end{array}$$

Ex:

$$A = \begin{pmatrix} 1 & 1 & 2 & 4 \\ 3 & 1 & 1 & 0 \\ 2 & 3 & 0 & 2 \\ 6 & 5 & 3 & 6 \end{pmatrix} \quad \begin{array}{l} |A| = \underline{0} \\ R(4) = R(1) + R(2) + R(3) \end{array}$$

② Minors and rank

A
max
matrix

Def: An r -minor of A is the determinant of an $r \times r$ submatrix of A

Ex: $A = \begin{pmatrix} 1 & 2 & 2 \\ 3 & 1 & 4 \end{pmatrix}$

2-minors:

$$M_{12,12} = \begin{vmatrix} 1 & 2 \\ 3 & 1 \end{vmatrix} = 1 - 6 = -5$$

$$M_{12,23} = \begin{vmatrix} 2 & 2 \\ 1 & 4 \end{vmatrix} = 8 - 2 = 6$$

$$M_{12,13} = \begin{vmatrix} 1 & 2 \\ 3 & 4 \end{vmatrix} = 4 - 6 = -2$$

1-minors:

$$\begin{array}{c} 1, 2, 2 \\ 3, 1, 4 \end{array}$$

Result: The rank of a max matrix A is maximal number r such that A has a non-zero r -minor.

$$\text{rk } A < r \iff \text{all } r\text{-minors of } A \text{ are zero.}$$

Ex: $A = \begin{pmatrix} 1 & 2 & 1 & 1 \\ 2 & 1 & -1 & 0 \\ 3 & 3 & 0 & 2 \end{pmatrix}$

$$A = \begin{pmatrix} 2 & 1 & 1 \\ 1 & -1 & 0 \\ 3 & 0 & 2 \end{pmatrix}$$

3-minors:

$$M_{123,123} = \begin{vmatrix} 1 & 2 & 1 \\ 2 & 1 & -1 \\ 3 & 3 & 0 \end{vmatrix} = 0$$

$$M_{123,234} = \begin{vmatrix} 2 & 1 & 1 \\ 1 & -1 & 0 \\ 3 & 0 & 2 \end{vmatrix} = -3$$

$$|A| = 1 \cdot (-3) + 2 \cdot (-3) = -3 \neq 0$$

$$\text{rk } A = \underline{\underline{3}}$$

$$\text{rk } A = \underline{\underline{3}}$$

Ex: $A = \begin{pmatrix} \boxed{1} & 2 & 1 & 1 \\ 2 & 1 & -1 & 0 \\ 3 & 3 & 0 & 1 \end{pmatrix}$ $R(3) = R(1) + R(2)$

all 3-minors = 0 $\Rightarrow \text{rk } A < 3$

2-minors: $M_{12,12} = 1 - 4 \neq 0 \Rightarrow \text{rk } A = \underline{\underline{2}}$

Ex: $A = \begin{pmatrix} 1 & 1 & 1 \\ 1 & p & q \end{pmatrix}$

2-minors: $p-1, q-p, q-1$

$$p-1=0 \quad p=1$$

$$q-p=0$$

$$q-1=0 \quad q=1$$

$$(p, q) = (1, 1) : \text{rk } A < 2$$

$$(p, q) \neq (1, 1) : \text{rk } A = 2$$

Conclusion:

$$\text{rk } A = \begin{cases} 2 & , (p, q) \neq (1, 1) \\ 1 & , (p, q) = (1, 1) \end{cases}$$

③ Solving linear systems using minors

$$\begin{aligned} \text{Ex: } \underline{x} + y + z + w &= 5 \\ 2x - y + 3z + 4w &= 2 \\ 3x \quad + 4z + 6w &= -1 \end{aligned}$$

$$A = \begin{pmatrix} 1 & 1 & 1 & 1 \\ 2 & -1 & 3 & 4 \\ 3 & 0 & 4 & 6 \end{pmatrix}$$



$$\begin{aligned} x + y + w &= 5 - z \\ 2x - y + 4w &= 2 - 3z \\ 3x \quad + 6w &= -1 - 4z \end{aligned}$$

3-minors:

$$M_{123,123} = 0$$

$$M_{123,124} = \begin{vmatrix} 1 & 1 & 1 \\ 2 & -1 & 4 \\ 3 & 0 & 6 \end{vmatrix}$$

$$= 3 \cdot (5) + 6 \cdot (-3) = -3 \neq 0$$

$$\Rightarrow \text{rk } A = 3$$

$$\text{2-minors: } \begin{vmatrix} 1 & 1 \\ 2 & -1 \end{vmatrix} = -1 - 2 = -3 \neq 0$$

M_{112}

\Rightarrow one degree of freedom
(z is free) infinitely many solutions

$$\begin{pmatrix} 1 & 1 & 1 \\ 2 & -1 & 4 \\ 3 & 0 & 6 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \\ w \end{pmatrix} = \begin{pmatrix} 5 - z \\ 2 - 3z \\ -1 - 4z \end{pmatrix}$$

$$\begin{pmatrix} x \\ y \\ w \end{pmatrix} = \begin{pmatrix} 1 & 1 & 1 \\ 2 & -1 & 4 \\ 3 & 0 & 6 \end{pmatrix}^{-1} \cdot \begin{pmatrix} 5 - z \\ 2 - 3z \\ -1 - 4z \end{pmatrix}$$

$$= \frac{1}{-3} \begin{pmatrix} -6 & 0 & 3 \\ -6 & 3 & 3 \\ 5 & -2 & -3 \end{pmatrix}^{-T} \cdot \begin{pmatrix} 5 - z \\ 2 - 3z \\ -1 - 4z \end{pmatrix}$$

$$\begin{pmatrix} x \\ y \\ w \end{pmatrix} = -\frac{1}{3} \begin{pmatrix} -6 & -6 & 5 \\ 0 & 3 & -2 \\ 3 & 3 & -3 \end{pmatrix} \begin{pmatrix} 5 - z \\ 2 - 3z \\ -1 - 4z \end{pmatrix} = -\frac{1}{3} \begin{pmatrix} 4z - 4z \\ -z + 8 \\ 24 \end{pmatrix} = \begin{pmatrix} -4z/3 + 4z/3 \\ z/3 - 8/3 \\ -8 \end{pmatrix}$$

$$\begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix} = \begin{pmatrix} -4z/3 + 4z/3 \\ z/3 - 8/3 \\ z \\ -8 \end{pmatrix}$$

where z is free