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 Plan
 

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- 1 Second order differential equations
  - 2 Linear second order differential equations
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Review:

First order differential equations

- separable
- exact
- linear

$$y' = F(t, y)$$

### ① Second order differential equations

A differential equation that involves  $y''$ , but no higher derivatives, is called a second order differential equation.

Ex:

$$y'' = 12t - 4 \quad | \int - dt$$

$$y' = \int 12t - 4 dt$$

$$= 12 \cdot \frac{t^2}{2} - 4t + C$$

$$y' = 6t^2 - 4t + C \quad | \int - dt$$

$$y = \int 6t^2 - 4t + C dt$$

$$= 6 \cdot \frac{t^3}{3} - 4 \frac{t^2}{2} + Ct + D$$

$$y = \underline{\underline{2t^3 - 2t^2 + Ct + D}}$$

general solution

depends on  
two undetermined  
coefficients

## ② Linear second order differential equations

Defn: A linear second order differential equation is a differential equation that can be written

$$y'' + a(t) \cdot y' + b(t) \cdot y = h(t)$$

We say that it is homogeneous if  $h(t) = 0$ , and it has constant coefficients if  $a(t) = a$  and  $b(t) = b$  are constants.

We are going to explain how to find the general solution in the case with constant coefficients.

### (a) Solution method in the homogeneous case

Ex:  $y'' - 3y' + 2y = 0$

Characteristic equation:  $r^2 - 3r + 2 = 0$   
 $(r-2)(r-1) = 0$   
 $r = 2$  or  $r = 1$

$$y = C_1 e^{2t} + C_2 e^t$$

(general solution)

$$r^2 + ar + b = 0 \quad \begin{matrix} \alpha \\ \beta \end{matrix}$$

$$r = \frac{-a \pm \sqrt{a^2 - 4b}}{2} = \frac{-a}{2} \pm \frac{\sqrt{4b - a^2}}{2} \cdot \sqrt{-1}$$

$$y'' + ay' + by = 0$$

Char. eqn:  $r^2 + ar + b = 0$   
 $r = \frac{-a \pm \sqrt{a^2 - 4b}}{2}$

$$\Delta = a^2 - 4b$$

$\Delta > 0$ : two distinct roots  $r_1 \neq r_2$   
 $y = C_1 e^{r_1 t} + C_2 e^{r_2 t}$

$\Delta = 0$ :  $r_1 = r_2 = -a/2$   
 $y = C_1 e^{-a/2 \cdot t} + C_2 t e^{-a/2 \cdot t}$

$\Delta < 0$ : no real roots  
 $y = e^{\alpha t} \cdot (C_1 \cos(\beta t) + C_2 \sin(\beta t))$

Ex:  $y'' + 6y' + 9y = 0$

$$r^2 + 6r + 9 = 0$$

( $\Delta = 0$ )  $r = \frac{-6 \pm \sqrt{36 - 4 \cdot 9}}{2}$

$$r_1 = r_2 = -3$$

$$y = \underline{\underline{C_1 \cdot e^{-3t} + C_2 t e^{-3t}}} = (C_1 + C_2 t) e^{-3t}$$

Ex:  $y'' - 4y' + 5y = 0$

$$r^2 - 4r + 5 = 0$$

$$r = \frac{4 \pm \sqrt{16 - 4 \cdot 5}}{2}$$

$$= \frac{4 \pm \sqrt{-4}}{2} = \frac{4 \pm \sqrt{4} \cdot \sqrt{-1}}{2}$$

( $\Delta < 0$ )  $= 2 \pm 1 \cdot \sqrt{-1}$

$\alpha = 2$     $\beta = 1$

$$y = \underline{\underline{e^{2t} (C_1 \cdot \cos t + C_2 \cdot \sin t)}}$$

Explanation of the characteristic eqn:

Look for solutions  
of the form  $y = e^{rt}$

$$\left. \begin{aligned} y &= e^{rt} = 1 \cdot e^{rt} \\ y' &= e^{rt} \cdot r = r \cdot e^{rt} \\ y'' &= r(e^{rt} \cdot r) = r^2 \cdot e^{rt} \end{aligned} \right\}$$

in  $y'' + ay' + by = 0$

$$r^2 e^{rt} + a(r e^{rt}) + b \cdot (1 \cdot e^{rt}) = 0$$

$$r^2 e^{rt} + a r e^{rt} + b e^{rt} = 0$$

$$(r^2 + ar + b) \cdot e^{rt} = 0$$

$$\underline{r^2 + ar + b = 0}$$

char. eqn.

Concl:

$e^{rt}$  is a solution of

$$y'' + ay' + by = 0$$



$$r^2 + ar + b = 0$$

$$y' + ay = 0$$

$$u = e^{\int a dt} = e^{at+C}$$

int. factor:  $e^{at}$

$$y' e^{at} + a y e^{at} = 0$$

$$(y \cdot e^{at})' = 0$$

$$y e^{at} = C$$

$$y = C \cdot e^{-at}$$

(b) Solution method in the inhomogeneous case

In general:  $y'' + ay' + by = h(t)$

Ex:  $y'' - 3y' + 2y = e^{-t}$  inhomogeneous

Solution method: Superposition principle

General solution:

$$y = \gamma_h + \gamma_p$$

the general solution of the homogeneous equation

$$y'' + ay' + by = 0$$

a particular solution of

$$y'' + ay' + by = h(t)$$

Ex:  $y'' - 3y' + 2y = e^{-t}$

Superposition:  $y = y_h + y_p = C_1 e^{2t} + C_2 e^t + \frac{1}{6} e^{-t}$

$y_h$ :  $y'' - 3y' + 2y = 0$

$$r^2 - 3r + 2 = 0$$

$$r = 2, r = 1 \Rightarrow$$

$$y_h = C_1 e^{2t} + C_2 e^t$$

$y_p$ :  $y'' - 3y' + 2y = e^{-t}$

"Guess"  $y = A \cdot e^{-t}$

$$y' = -A e^{-t}$$

$$y'' = A e^{-t}$$

$$(A e^{-t}) - 3(-A e^{-t}) + 2(A e^{-t}) = e^{-t}$$

$$(A + 3A + 2A) e^{-t} = e^{-t}$$

$$6A = 1 \Rightarrow A = \frac{1}{6} \Rightarrow y_p = \frac{1}{6} e^{-t}$$

Method of undetermined coeff:

How to "guess":

- should depend on parameters (A)
- should have the same form as  $h(t), h'(t), h''(t)$

$$e^{-t} \quad e^{-t} \quad e^{-t}$$

If it doesn't work, try to multiply with  $t$



Explanation: Superposition principle

$$y'' + a(t)y' + b(t)y = h(t)$$

linear second order differential equation

Differential operator

$$D = \frac{d^2}{dt^2} + a(t)\frac{d}{dt} + b(t) \quad ; \quad D(y(t)) = y'' + a(t)y' + b(t)y$$

Ex:  $y'' - 3y' + 2y = e^{-t}$   
 $D(y) = e^{-t}$  where  $D = \frac{d^2}{dt^2} - 3\frac{d}{dt} + 2$ .

$$D(t) = 0 - 3 \cdot 1 + 2t = -3 + 2t$$

$$D(e^{-t}) = (e^{-t})'' - 3 \cdot (e^{-t})' + 2 \cdot (e^{-t})$$

$$= e^{-t} - 3(-e^{-t}) + 2e^{-t} = 6e^{-t}$$

D is linear:  
differential operator

$$\textcircled{1} D(y_1 + y_2) = D(y_1) + D(y_2)$$

$$\textcircled{2} D(c \cdot y) = c \cdot D(y)$$

Applications:

i)  $D(e^{-t}) = 6e^{-t} \Rightarrow D\left(\frac{1}{6}e^{-t}\right) = \frac{1}{6}D(e^{-t})$   
 $= \frac{1}{6} \cdot 6e^{-t} = \underline{e^{-t}}$

ii)  $y'' - 3y' + 2y = 0$       $D = \frac{d^2}{dt^2} - 3\frac{d}{dt} + 2$

$$r^2 - 3r + 2 = 0$$

$$r = 2, r = 1 \Rightarrow$$

$e^{2t}, e^t$  are solutions

$y = C_1 e^{2t} + C_2 e^t$  is the general solution

Linear property:  $D(e^{2t}) = 0$   
 $D(e^t) = 0$

$$\Rightarrow D(C_1 e^{2t} + C_2 e^t) = D(C_1 e^{2t}) + D(C_2 e^t) = C_1 \cdot 0 + C_2 \cdot 0 = 0$$

iii) Superposition principle:

$= y_h + y_p$   
general solution

$y'' + a(t)y' + b(t)y = h(t)$   
 $D(y) = h(t)$

$D = \frac{d^2}{dt^2} + a(t)\frac{d}{dt} + b(t)$   
linear diff. operator

(a) Assume  $y = y_h + y_p$ , where

$y_h$ : general solution of the homogeneous equation

Then:

$D(y) = D(y_h + y_p)$   
 $= D(y_h) + D(y_p)$   
 $= 0 + h(t) = h(t)$   
 $\Rightarrow y$  is a solution

$D(y_h) = 0$

$y_p$ : particular solution  
 $D(y_p) = h(t)$

(b) Assume  $y$  is a solution, i.e.  $D(y) = h(t)$

Then

$D(y - y_p) = D(y) - D(y_p)$   
 $= h(t) - h(t) = 0$

$y_p$ : a particular solution,  
i.e.  $D(y_p) = h(t)$

$\Rightarrow y - y_p$  is a solution of the homogeneous eqn.

$\Rightarrow y - y_p = y_h \Rightarrow y = y_h + y_p$

Ex:  $y' - y = e^{2t}$   
 $D(y) = e^{2t}$

first order linear diff. eqn.

$D = \frac{d}{dt} - 1$

$D$  has the linear property:

$D(y_1 + y_2) = (y_1 + y_2)' - 1(y_1 + y_2)$   
 $= y_1' + y_2' - y_1 - y_2$   
 $= (y_1' - y_1) + (y_2' - y_2)$   
 $= D(y_1) + D(y_2)$

Can use superposition

$y = y_h + y_p = \underline{\underline{C e^t + e^{2t}}}$

$y_h$ :  $y' - y = 0$   
 $r - 1 = 0 \quad r = 1$   
 $y_h = C \cdot e^t$

$y_p$ :  $y' - y = e^{2t}$   
 $y = A e^{2t} \quad A = 1$   
 $y' = 2A e^{2t} \quad y_p = 1 \cdot e^{2t}$   
 $2A e^{2t} - A e^{2t} = e^{2t}$

$D(e^{2t}) = 2e^{2t} - e^{2t} = e^{2t}$   
 $y_p = e^{2t}$

$D(C \cdot y_1) = (C y_1)' - 1(C y_1)$   
 $= C y_1' - C \cdot 1 \cdot y_1$   
 $= C (y_1' - y_1)$   
 $= C \cdot D(y_1)$

## Summary: Linear differential eqn's

①  $y' + a(t)y = b(t)$  first order linear

②  $y'' + a(t)y' + b(t)y = h(t)$  second order linear

\* Superposition always works :  $y = y_h + y_p$

\* Characteristic eqn: works if ①  $a(t) = a$  constant

②  $a(t) = a$  constant  
 $b(t) = b$



Plan

- 1 Equilibrium states and stability
- 2 Superposition principle

① Equilibrium states and stability:

Defn: A first order differential eqn. is called autonomous if it can be written  $y' = F(y)$  ← no  $t$  in the diff. eqn.

Ex:

$$y' = 2y$$

$$y' = 5y \cdot (1 - y/10)$$

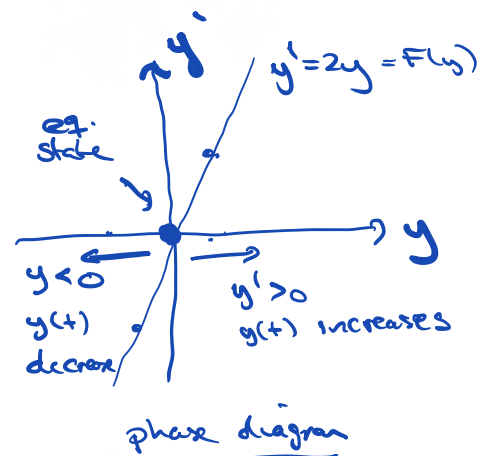
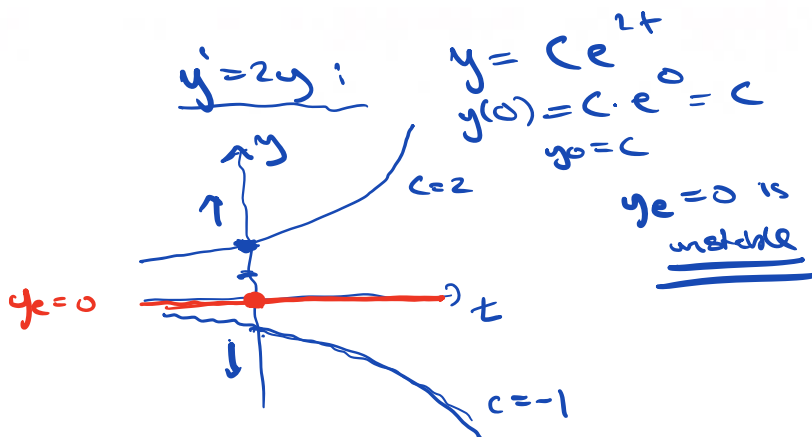
A equilibrium state of  $y' = F(y)$  is value  $y = y_e$  such that  $F(y_e) = 0$

Ex: 1)  $y' = 2y$

Eg. states:  $2y = 0$   
 $y = 0 \Rightarrow \underline{\underline{y_e = 0}}$

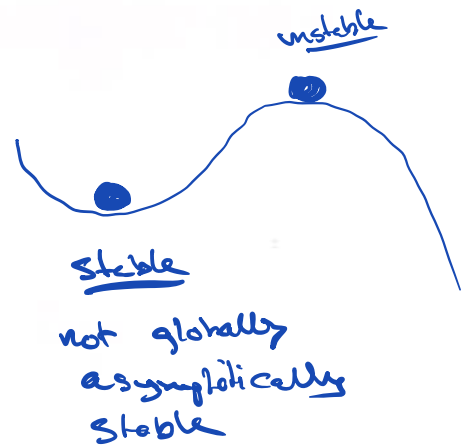
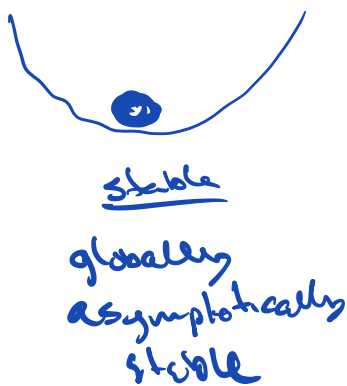
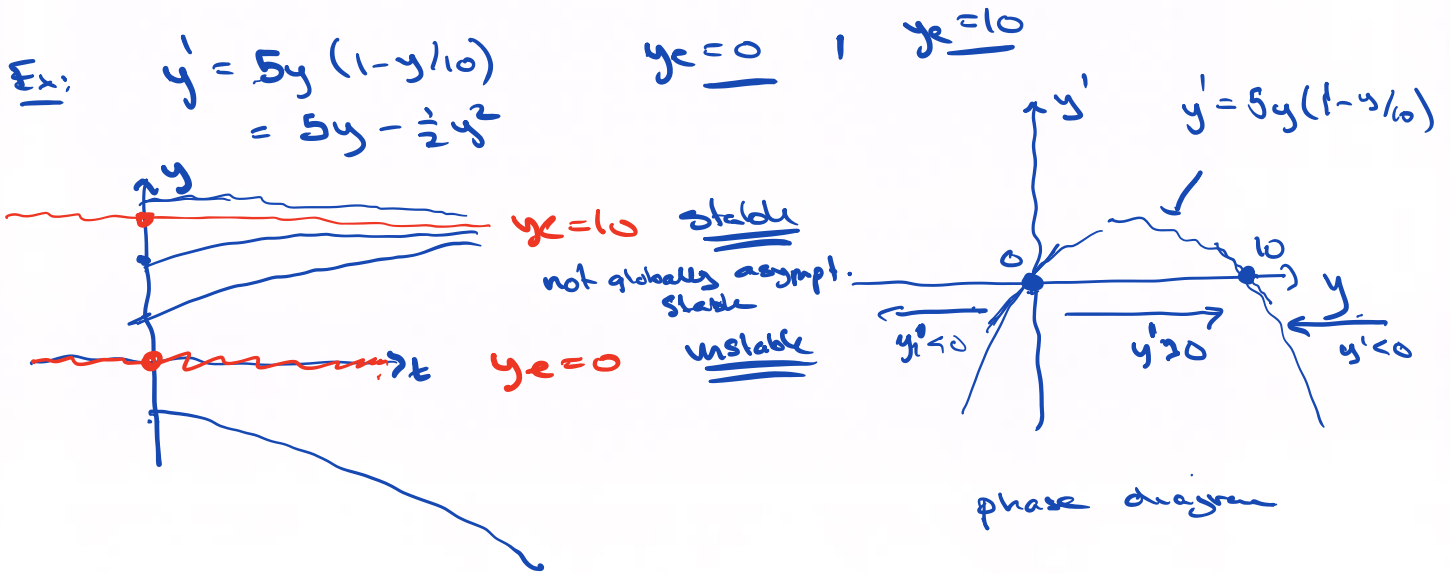
2)  $y' = 5y(1 - y/10)$

Eg. states:  $5y(1 - y/10) = 0$   
 $y = 0$  or  $y = 10$   
 $5y = 0$       $1 - y/10 = 0$   
 $\parallel$   
 $y_e = 0, y_e = 10$



If  $y_0 = 0$ :  $y = 0$

- Defn.: An eq. state  $y = y_e$  is called
- i) stable if  $y_0$  close  $y_e$  means that  $y(t)$  moves towards  $y_e$  ———— moves
  - ii) unstable if  $y_0$  ———— further away from  $y_e$
  - iii) globally asymptotically stable if  $y(t)$  moves towards  $y_e$  no matter which starting point  $y_0$  you consider



Stability Thm.

If  $y = y_e$  is an eq. state of  $y' = F(y)$ , then we have:

$F'(y_e) > 0 \Rightarrow y_e$  is unstable

$F'(y_e) < 0 \Rightarrow y_e$  is stable