

Inverse matrices

EBA1180
Spring 25
Sect. 37

Ex: $2x + y = 4$
 $x + 2y = 3$

Matrix form:

$$\underbrace{\begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}}_A \underbrace{\begin{bmatrix} x \\ y \end{bmatrix}}_{\vec{x}} = \underbrace{\begin{bmatrix} 4 \\ 3 \end{bmatrix}}_{\vec{b}}$$

If A^{-1} exists:

$$\underbrace{A^{-1}}_I A \vec{x} = A^{-1} \vec{b}$$

$$I \vec{x} = A^{-1} \vec{b}$$

$$\boxed{\vec{x} = A^{-1} \vec{b}}$$

Advantage of A^{-1} :
Quickly solve
lin. syst. with
many different
r. h. s.

$$\vec{x} = \frac{1}{3} \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} 4 \\ 3 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 8 - 3 \\ -4 + 6 \end{bmatrix}$$

$$= \frac{1}{3} \begin{bmatrix} 5 \\ 2 \end{bmatrix} = \begin{bmatrix} \frac{5}{3} \\ \frac{2}{3} \end{bmatrix}$$

So: $(x, y) = \left(\frac{5}{3}, \frac{2}{3} \right)$

Computing inverse matrices

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 4 \\ 1 & 3 & 9 \end{bmatrix}$$

$$\begin{bmatrix} + & - & + \\ - & + & - \\ + & - & + \end{bmatrix}$$

$$c_{ij} = (-1)^{i+j} M_{ij}$$

$$|A| = 1(18^6 - 12) - 1(9^5 - 4) + 1(3 - 2)$$

$$= 2 \neq 0 \text{ so } A \text{ has an inverse.}$$

Use formula to find A^{-1} :

$$A^{-1} = \frac{1}{|A|} \begin{bmatrix} c_{11} & c_{12} & c_{13} \\ c_{21} & c_{22} & c_{23} \\ c_{31} & c_{32} & c_{33} \end{bmatrix}^T \left. \vphantom{\begin{bmatrix} c_{11} & c_{12} & c_{13} \\ c_{21} & c_{22} & c_{23} \\ c_{31} & c_{32} & c_{33} \end{bmatrix}} \right\} \begin{array}{l} \text{Adjoint} \\ \text{matrix of} \\ A: \\ \text{adj}(A) \end{array}$$

Compute c_{ij} 's:

$$c_{11} = 6$$

$$c_{12} = -5$$

$$c_{13} = 1$$

$$c_{21} = -6$$

$$c_{22} = 8$$

$$c_{23} = -2$$

$$c_{31} = 2$$

$$c_{32} = -3$$

$$c_{33} = 1$$

$$A^{-1} = \frac{1}{2} \begin{bmatrix} 6 & -5 & 1 \\ -6 & 8 & -2 \\ 2 & -3 & 1 \end{bmatrix}^T$$

$$= \frac{1}{2} \begin{bmatrix} 6 & -6 & 2 \\ -5 & 8 & -3 \\ 1 & -2 & 1 \end{bmatrix}$$

Alternative way of finding A^{-1} :

A
 $n \times n$
matrix

$$[A \mid I] \sim \dots \sim [B \mid C]$$

Reduced echelon form:

Aim for $B = I$

2 cases:

$B = I$

$A^{-1} = C$

$B \neq I$: A^{-1} doesn't exist.

Ex: $A = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$, seen before:

$$A^{-1} = \frac{1}{3} \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix} = \begin{bmatrix} \frac{2}{3} & -\frac{1}{3} \\ -\frac{1}{3} & \frac{2}{3} \end{bmatrix}$$

Alternative method:

$$\left[\begin{array}{cc|cc} 2 & 1 & 1 & 0 \\ 1 & 2 & 0 & 1 \end{array} \right] \sim \left[\begin{array}{cc|cc} 1 & 2 & 0 & 1 \\ 2 & 1 & 1 & 0 \end{array} \right]$$

A I

$$\sim \left[\begin{array}{cc|cc} 1 & 2 & 0 & 1 \\ 0 & -3 & 1 & -2 \end{array} \right] \begin{array}{l} | : (-3) \end{array} \sim \left[\begin{array}{cc|cc} 1 & 2 & 0 & 1 \\ 0 & 1 & -\frac{1}{3} & \frac{2}{3} \end{array} \right]$$

Echelon form

$$\sim \left[\begin{array}{cc|cc} 1 & 0 & \frac{2}{3} & -\frac{1}{3} \\ 0 & 1 & -\frac{1}{3} & \frac{2}{3} \end{array} \right]$$

Reduced echelon form

$$= [I \mid A^{-1}], \text{ so}$$

$$A^{-1} = \begin{bmatrix} \frac{2}{3} & -\frac{1}{3} \\ -\frac{1}{3} & \frac{2}{3} \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix}$$

Why does this work? 3×3

$$A = \begin{bmatrix} 1 & \dots \\ 2 & \dots \\ \dots & \dots \end{bmatrix} \xrightarrow[-2]{\sim} \begin{bmatrix} 1 & \dots \\ 0 & \dots \\ \dots & \dots \end{bmatrix} = B, \text{ then}$$

$$B = E_1 \cdot A$$

1st elementary row op.
elementary matrix

$$E_1 = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix};$$

the matrix found by doing the elementary row operation on the identity matrix:

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow[-2]{\sim} \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = E_1$$

Each row operation corresponds to matrix multiplication (4)

START: 13.00

$$[A \mid I] \sim \dots \sim [B \mid C]$$



$$E_r \dots E_2 E_1 A = B$$



Multiply with one elementary matrix for each row op.

and

$$E_r \dots E_2 E_1 I = C$$

Then, if $B=I$:

$$E_r \dots E_2 E_1 A = I$$

$$E_r \dots E_2 E_1 = C$$

So:

$$C A = I$$

$$A^{-1}$$

If $B \neq I$: $|A| = 0 \Rightarrow$ No inverse.

Will have 0 in diagonal $\Rightarrow |B|=0$.

But $|A| = |B|$ · scaling · switch sign

$$\Rightarrow |A| = 0$$

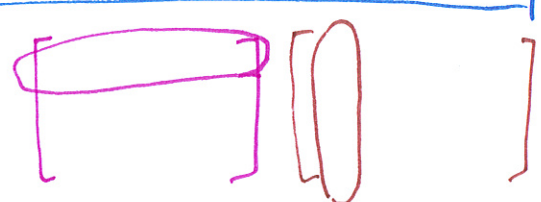
Inner product (dot product) of vectors

Def (Inner product): Let \vec{v}, \vec{w} be n -vectors

$$\vec{v} = \begin{bmatrix} v_1 \\ \vdots \\ v_n \end{bmatrix}, \vec{w} = \begin{bmatrix} w_1 \\ \vdots \\ w_n \end{bmatrix}. \text{ Then,}$$

$$\vec{v} \cdot \vec{w} = v_1 w_1 + v_2 w_2 + \dots + v_n w_n$$

dot



Ex: $\vec{v} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \vec{w} = \begin{bmatrix} 3 \\ -1 \end{bmatrix}$

$$\vec{v} \cdot \vec{w} = 1 \cdot 3 + 2 \cdot (-1) = 3 - 2 = \underline{\underline{1}}$$

Read: " \vec{v} dot \vec{w} "

Exercise sheet 35

7) b), c), d)

Profit per stock:

	A ^x	B ^y	C ^z
1	20	5	30
2	40	-50	180
3	-20	25	-265

Profit from owning 1 unit of stocks A, B, C resp. in scenario 3

↳ Profit for owning 1 unit of stock A in each of the 3 scenarios

Budget constraint: $60x + 75y + 320z = C$

Which ~~profits~~ profits are possible?

400000



Profits: (R_1, R_2, R_3)

Profit in scenario 1:

$$20x + 5y + 30z = R_1$$

Profit in scenario 2:

$$40x - 50y + 180z = R_2$$

Profit in scenario 3:

$$-20x + 25y - 265z = R_3$$

+ budget constraint: Gaussian elimination:

$$\left[\begin{array}{ccc|c} 20 & 5 & 30 & R_1 \\ 40 & -50 & 180 & R_2 \\ -20 & 25 & -265 & R_3 \\ 60 & 75 & 320 & C \end{array} \right] \begin{array}{l} \\ \leftarrow -2 \\ \leftarrow 1 \\ \leftarrow -3 \end{array}$$

$$\sim \left[\begin{array}{ccc|c} 20 & 5 & 30 & R_1 \\ 0 & -60 & 120 & R_2 - 2R_1 \\ 0 & 30 & -235 & R_3 + R_1 \\ 0 & 60 & 230 & C - 3R_1 \end{array} \right] \begin{array}{l} \\ \leftarrow 2 \\ \leftarrow 1 \end{array}$$

$$\sim \left[\begin{array}{ccc|c} 20 & 5 & 30 & R_1 \\ 0 & -60 & 120 & R_2 - 2R_1 \\ 0 & 0 & -175 & R_3 + R_1 + \frac{1}{2}(R_2 - 2R_1) \\ 0 & 0 & 350 & C - 3R_1 + (R_2 - 2R_1) \end{array} \right] \downarrow \leftarrow 2$$

$$\sim \left[\begin{array}{ccc|c} 20 & 5 & 30 & R_1 \\ 0 & -60 & 120 & R_2 - 2R_1 \\ 0 & 0 & -175 & R_3 + \frac{1}{2}R_2 \\ 0 & 0 & 0 & C - 5R_1 + 2R_2 + 2R_3 \end{array} \right]$$

For system to have a solution, must have:

$$C - 5R_1 + 2R_2 + 2R_3 = 0$$