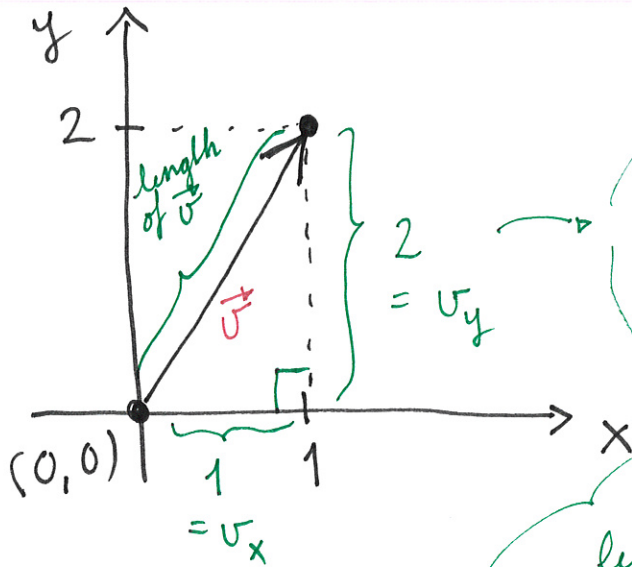


Geometric interpretation of vectors

EBA1180
Sect. 33
Spring 24

Ex: $\vec{v} = \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} v_x \\ v_y \end{bmatrix}$

corresp. to an arrow from $(0, 0)$ to (v_x, v_y)
 $(1, 2)$



Pythagorean theorem:

$$v_x^2 + v_y^2 = (\text{length of } \vec{v})^2$$

$$\text{length of } \vec{v} = \sqrt{v_x^2 + v_y^2}$$

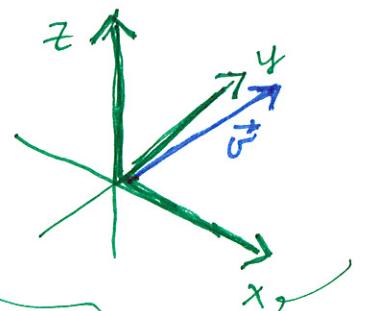
• A vector has length (magnitude)

and a direction.

$$\|\vec{v}\| = \left\| \begin{bmatrix} v_x \\ v_y \end{bmatrix} \right\| = \sqrt{v_x^2 + v_y^2}$$

Ex: $\|\vec{v}\| = \sqrt{1^2 + 2^2} = \underline{\underline{\sqrt{5}}}$

3-dimensions:



Def: (length of vector)

If $\vec{v} = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix}$, then

$$\|\vec{v}\| = \sqrt{v_1^2 + v_2^2 + \dots + v_n^2}$$

Ex: $\vec{v} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$, $\vec{w} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$

ADD:

$$\vec{v} + \vec{w} = \begin{bmatrix} 1+2 \\ 2+1 \end{bmatrix} = \begin{bmatrix} 3 \\ 3 \end{bmatrix}$$

SCALAR
MULTIPLICATION:

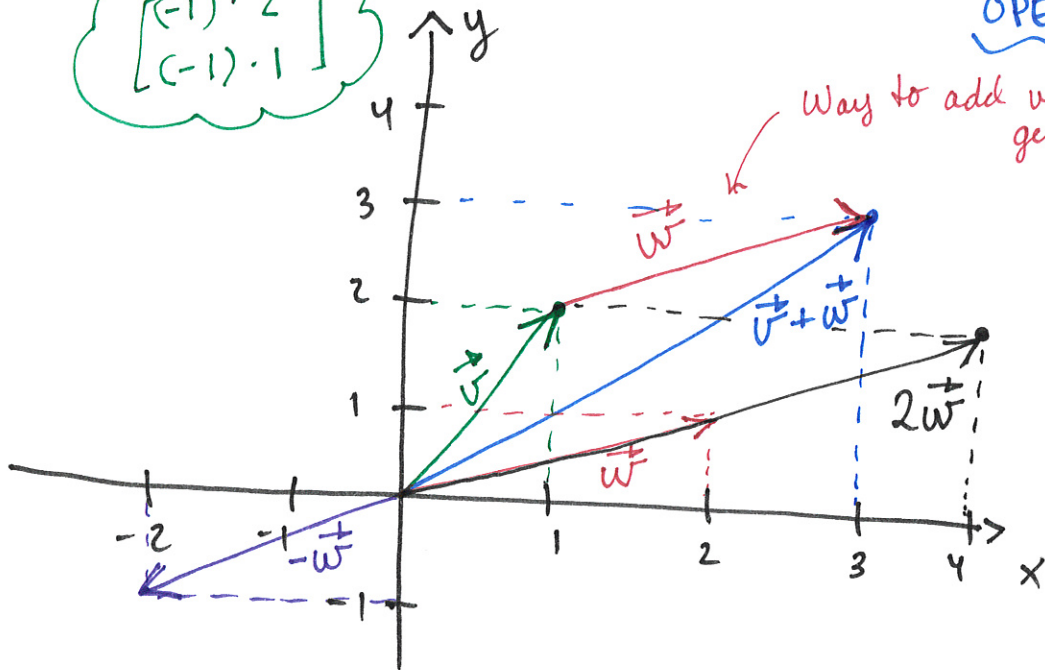
$$2\vec{w} = \begin{bmatrix} 2 \cdot 2 \\ 2 \cdot 1 \end{bmatrix} = \begin{bmatrix} 4 \\ 2 \end{bmatrix}$$

$$(-1)\vec{w} = -\vec{w} = \begin{bmatrix} -2 \\ -1 \end{bmatrix}$$

$\begin{bmatrix} (-1) \cdot 2 \\ (-1) \cdot 1 \end{bmatrix}$

VISUALIZE VECTOR
OPERATIONS:

Way to add vectors
geometrically



Determinants

A
 $n \times n$
matrix



"the determinant of A "

$$\det(A) = |A|$$

a number

(square ∇)

Ex: $A = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$, $\det(A) = \begin{vmatrix} 2 & 1 \\ 1 & 2 \end{vmatrix}$

2×2

$$= 2 \cdot 2 - 1 \cdot 1$$

$$= \underline{\underline{3}}$$

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}, \det(A) = \begin{vmatrix} a & b \\ c & d \end{vmatrix}$$

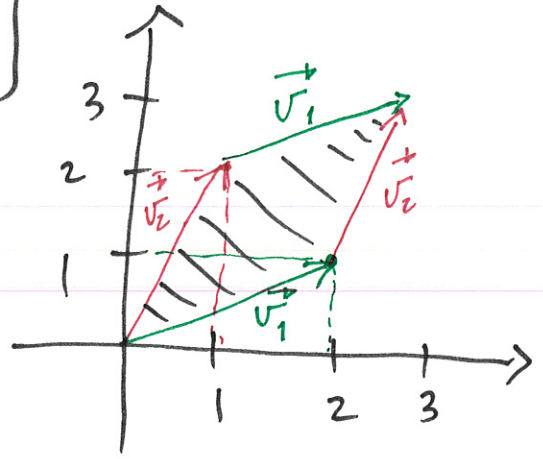
$$= ad - bc$$

FORMULA: (Determinant, $n=2$)

$$\begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc$$

Interpretation: $A = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$

$$\vec{v}_1 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}, \quad \vec{v}_2 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$



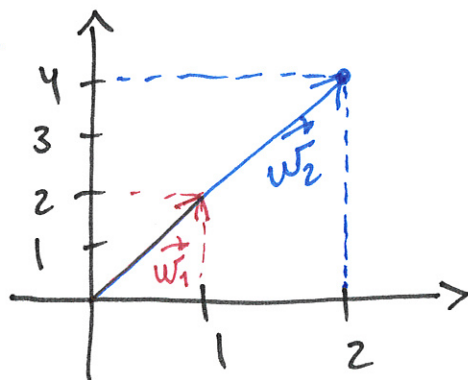
$$\det(A) = \begin{vmatrix} 2 & 1 \\ 1 & 2 \end{vmatrix} = \underline{3}$$

Can prove: $|\det(A)| = \text{area of parallelogram spanned by } \vec{v}_1 \text{ and } \vec{v}_2.$

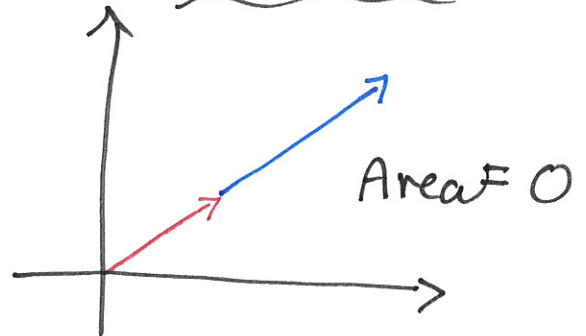
NOTE: $\begin{vmatrix} \vec{v}_2 & \vec{v}_1 \end{vmatrix} = \begin{vmatrix} 1 & 2 \\ 2 & 1 \end{vmatrix} = 1 \cdot 1 - 2 \cdot 2 = \underline{-3}$

Area can't be neg: Need abs. value

EX: $\begin{vmatrix} 1 & 2 \\ 2 & 4 \end{vmatrix} = 1 \cdot 4 - 2 \cdot 2 = 0$



Parallelogram spanned by \vec{w}_1 & \vec{w}_2 :



$(\vec{v}_1 \text{ and } \vec{v}_2 \text{ are scalar multiples})$

Ex: $A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 4 \\ 1 & 3 & 9 \end{bmatrix}$ 3×3 ; square

$$\begin{vmatrix} 1 & 1 & 1 \\ 1 & 2 & 4 \\ 1 & 3 & 9 \end{vmatrix} = 1 \cdot C_{11} + 1 \cdot C_{12} + 1 \cdot C_{13}$$

cofactor expansion along row 1

where C_{11}, C_{12}, C_{13} are

cofactors:

$$C_{ij} = (-1)^{i+j} \cdot M_{ij}$$

where M_{ij} is the determinant of the submatrix you get when you delete row i , column j .

minor

$$\begin{bmatrix} + & - & + \\ - & + & - \\ + & - & + \end{bmatrix}$$

So:

$$\begin{vmatrix} 1 & 1 & 1 \\ 1 & 2 & 4 \\ 1 & 3 & 9 \end{vmatrix} = 1 \cdot \begin{vmatrix} 2 & 4 \\ 3 & 9 \end{vmatrix} + 1 \cdot (-1) \begin{vmatrix} 1 & 4 \\ 1 & 9 \end{vmatrix} + 1 \begin{vmatrix} 1 & 2 \\ 1 & 3 \end{vmatrix}$$

$$= 18 - 12 - (9 - 4) + 3 - 2$$

$$= 6 - 5 + 1 = \underline{\underline{2}}$$

NOTE: \rightarrow Cofactor expansion along any row / column gives the same result.

\rightarrow Any determinant can be computed by cofactor expansion.

$$\begin{bmatrix} + & - & + & - \\ - & + & - & + \\ + & - & + & - \\ - & + & - & + \end{bmatrix}$$

Ex:

$$\begin{vmatrix} 1 & 1 & 1 & 1 \\ 1 & 2 & 4 & 8 \\ 1 & 3 & 9 & 27 \\ 1 & -1 & 1 & -1 \end{vmatrix} = 1 \cdot \begin{vmatrix} 2 & 4 & 8 \\ 3 & 9 & 27 \\ -1 & 1 & -1 \end{vmatrix} - 1 \cdot \begin{vmatrix} 1 & 4 & 8 \\ 1 & 9 & 27 \\ 1 & 1 & -1 \end{vmatrix} + 1 \cdot \begin{vmatrix} 1 & 2 & 8 \\ 1 & 3 & 27 \\ 1 & -1 & -1 \end{vmatrix} - 1 \cdot \begin{vmatrix} 1 & 2 & 4 \\ 1 & 3 & 9 \\ 1 & -1 & 1 \end{vmatrix} = \dots$$

→ Exploit the 0's ∇ Use row/column with lots of 0's to simplify computations.

Connection between the # solutions of linear systems and determinants

- If you start with $n \times n$ linear system (# eqns = # variables), then the corresp. coefficient matrix is an $n \times n$ matrix.

Ex:

$$\begin{aligned}x + y + z &= 3 \\x + 2y + 4z &= 7 \\x + 3y + 9z &= 13\end{aligned}$$

3×3 linear system

Write this as: $A \vec{x} = \vec{b}$ (matrix form)

where

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 4 \\ 1 & 3 & 9 \end{bmatrix}, \quad \vec{x} = \begin{bmatrix} x \\ y \\ z \end{bmatrix}, \quad \vec{b} = \begin{bmatrix} 3 \\ 7 \\ 13 \end{bmatrix}$$

Coefficient matrix; 3×3 matrix

→ Since coefficient matrix of $n \times n$ lin. syst. is an $n \times n$ matrix, we can $|A|$.

Result: i) $|A| \neq 0 \Rightarrow$ One unique solution
not equal to n

ii) $|A| = 0 \Rightarrow$ No solutions or infinitely many solutions.

Theorem (Cramer's rule):

Consider a linear system, $A\vec{x} = \vec{b}$, with coefficient matrix A and r.h.s. \vec{b} , s.t.

A is square ($n \times n$) with $|A| \neq 0$. Then, the solution of the linear system is:

$$x_1 = \frac{|A_1(\vec{b})|}{|A|}, \quad x_2 = \frac{|A_2(\vec{b})|}{|A|}, \quad \dots,$$

$$x_n = \frac{|A_n(\vec{b})|}{|A|}$$

where $A_i(\vec{b})$ is the matrix you get when you replace the i 'th column in A with \vec{b} .



Ex: $x + y = 4$, x, y : variables
 $x + ay = 6$ a : parameter