

More linear systems:

Number of solutions

6/2-24
EBA 1180
Sect. 32

Ex: $x_1 + x_2 + x_3 + x_4 + x_5 = 17$

$$x_1 - 2x_2 - x_3 + 4x_5 = 8$$

$$2x_1 + x_2 - 5x_3 + 7x_4 = 11$$

Def (Pivot position):

A pivot position is a position where there is a pivot in the echelon form.

Ex ctd:

$$\left[\begin{array}{ccccc|c} 1 & 1 & 1 & 1 & 1 & 17 \\ 1 & -2 & -1 & 0 & 4 & 8 \\ 2 & 1 & -5 & 7 & 0 & 11 \end{array} \right]$$

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Add $(-1) \cdot$ row 1 to row 2
Add $(-2) \cdot$ row 1 to row 3

$$\left[\begin{array}{ccccc|c} 1 & 1 & 1 & 1 & 1 & 17 \\ 0 & -3 & -2 & -1 & 3 & -9 \\ 0 & -1 & -7 & 5 & -2 & -23 \end{array} \right]$$

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switch rows 2 & 3

$$\left[\begin{array}{ccccc|c} 1 & 1 & 1 & 1 & 1 & 17 \\ 0 & -1 & -7 & 5 & -2 & -23 \\ 0 & -3 & -2 & -1 & 3 & -9 \end{array} \right]$$

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add $(-3) \times$
row 2 to
row 3

$$\left[\begin{array}{ccccc|c} 1 & 1 & 1 & 1 & 1 & 17 \\ 0 & -1 & -7 & 5 & -2 & -23 \\ 0 & 0 & 19 & -16 & 9 & 60 \end{array} \right]$$

Echelon form!

Pivots! Pivot positions are
 $(1, 1), (2, 2), (3, 3)$.

The linear system has two degrees of freedom
(x_4, x_5 are free). Hence, it has infinitely many
solutions.

Why? From echelon form

$$\begin{aligned} x_1 + x_2 + x_3 + x_4 + x_5 &= 17 \\ -x_2 - 7x_3 + 5x_4 - 2x_5 &= -23 \\ \cdot \quad 19x_3 - 16x_4 + 9x_5 &= 60 \Rightarrow \end{aligned}$$

$$19x_3 = 60 + 16x_4 - 9x_5$$

\vdots

$$x_2 = \dots \text{ via } x_4 \text{ and } x_5 \dots$$

$$x_1 = \dots \text{ via } x_4 \text{ and } x_5 \dots$$

\Rightarrow Can choose any x_4 and x_5 and the original linear system still holds.

Result: For any linear system, the pivot positions determine the number of solutions.

Different cases:

i) Pivot position in the last column:

No solutions.

Ex:

$$\left[\begin{array}{ccc|c} \vdots & \vdots & \vdots & \vdots \\ 0 & \dots & 0 & 1 \end{array} \right]$$

Says:

$0 = 1$; Never true

ii) No pivot position in the last column:

The linear system has solutions.

a) Pivot positions in all variable columns:

One solution

Ex: $\left[\begin{array}{ccc|c} \textcircled{1} & \dots & \dots & \vdots \\ 0 & \textcircled{1} & \dots & \vdots \\ 0 & 0 & \textcircled{1} & \vdots \end{array} \right] \rightarrow \begin{array}{l} x_2 = \dots \\ x_3 = \text{number} \end{array}$

b) There are variable columns without pivot positions: Infinitely many solutions

Ex: $\left[\begin{array}{ccc|c} 1 & \dots & \dots & \vdots \\ 0 & 1 & \dots & \vdots \\ 0 & 0 & 1 & \dots \end{array} \right]$

Theorem: Any linear system has

either:

- i) No solutions \leadsto Inconsistent
- ii) One unique solution \leadsto Consistent
- iii) Infinitely many solutions.

Computations with matrices and vectors

Def ($m \times n$ matrix):

An $m \times n$ matrix is a rectangular array of numbers with m rows and n columns.

Ex: $A = \begin{bmatrix} 1 & 2 & 4 \\ 7 & -1 & 0 \end{bmatrix}$ } 2 rows

Capital letters for matrices

3 columns

Dimension: 2×3 matrix

Read: "2 by 3" or "2 times 3"

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \end{bmatrix} \begin{matrix} 1 \\ 2 \end{matrix}$$

a_{12} column 2

row 1

- Addition: $A + B$
 - Subtraction: $A - B$
- Defined if A and B have the same size (e.g. both $m \times n$)

Result is a matrix of the same size as A/B

- Scalar multiplication:

$$r \cdot A$$

Result is a matrix of same size as A

r : scalar (number)

A : matrix

Always defined

Ex:

$$\begin{bmatrix} 1 & 2 & 3 \\ -1 & 0 & 2 \end{bmatrix} + \begin{bmatrix} 0 & -1 & 1 \\ 1 & 2 & 3 \end{bmatrix}$$

$$= \begin{bmatrix} 1+0 & 2+(-1) & 3+1 \\ -1+1 & 0+2 & 2+3 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 4 \\ 0 & 2 & 5 \end{bmatrix}$$

Do addition/subtraction position by position.


Ex:

$$2 \cdot \begin{bmatrix} 1 & 4 \\ -1 & 2 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 2 \cdot 1 & 2 \cdot 4 \\ 2 \cdot (-1) & 2 \cdot 2 \\ 2 \cdot 0 & 2 \cdot 1 \end{bmatrix} = \begin{bmatrix} 2 & 8 \\ -2 & 4 \\ 0 & 2 \end{bmatrix}$$

Do multiplication by scalar position by position.

Def (n-vector)

An n-vector is a matrix with n rows and 1 column (a column vector).

• Write vectors  as $\vec{v} = \text{boldface } \mathbf{v} = \underline{v}$

EX: $\vec{v} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$; a 3-vector viewed as a column vector

Vector operations

lower case letters for vectors

→ Addition: $\vec{v} + \vec{w}$

→ Subtraction: $\vec{v} - \vec{w}$

→ Scalar multiplication: $r \cdot \vec{v}$ (r scalar) \rightarrow number

EX:
ADD: $\begin{bmatrix} 1 \\ 2 \end{bmatrix} + \begin{bmatrix} 2 \\ -1 \end{bmatrix} = \begin{bmatrix} 1+2 \\ 2+(-1) \end{bmatrix} = \underline{\underline{\begin{bmatrix} 3 \\ 1 \end{bmatrix}}}$

SUBTRACT: $\begin{bmatrix} 1 \\ 2 \end{bmatrix} - \begin{bmatrix} 2 \\ -1 \end{bmatrix} = \begin{bmatrix} 1-2 \\ 2-(-1) \end{bmatrix} = \underline{\underline{\begin{bmatrix} -1 \\ 3 \end{bmatrix}}}$

SCALAR
MULTIPLICATION:

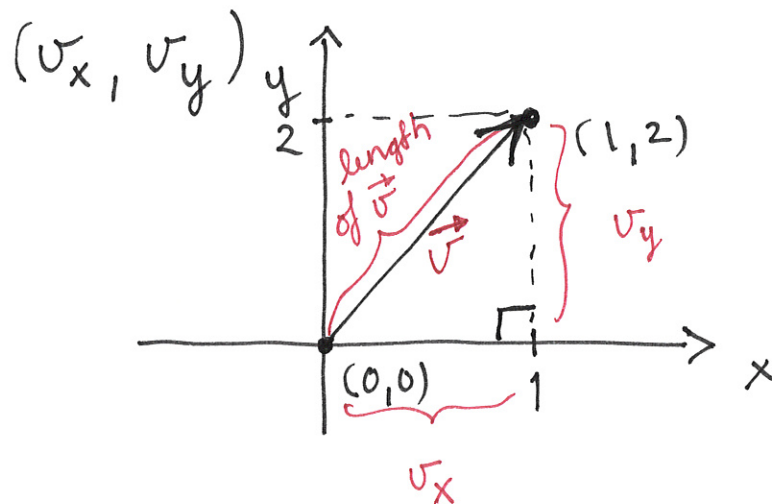
$$2 \cdot \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 2 \cdot 1 \\ 2 \cdot 2 \end{bmatrix} = \begin{bmatrix} 2 \\ \underline{\underline{4}} \end{bmatrix}$$

$$(-1) \cdot \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} -1 \\ \underline{\underline{-2}} \end{bmatrix}$$

Geometric interpretation of vectors

Ex: $\vec{v} = \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} v_x \\ v_y \end{bmatrix}$

corresponds to an arrow from $(0, 0)$ to



A vector has a length (magnitude) and a direction.