

QUESTION 1.

- (a) The determinant of
- A
- is

$$\det(A) = \begin{vmatrix} -2 & 2 & 0 \\ -1 & 0 & 2 \\ 0 & -1 & 2 \end{vmatrix} = -2(2) - 2(-2) = 0$$

This means that $\text{rk}(A) < 3$, and since at least one of the 2-minors are non-zero, for instance

$$\begin{vmatrix} -2 & 2 \\ -1 & 0 \end{vmatrix} = 2 \neq 0$$

it follows that $\text{rk}(A) = 2$.

- (b) The linear system
- $A\mathbf{x} = \mathbf{0}$
- has one free variables since
- A
- has rank two, and we compute the solutions using Gaussian elimination:

$$\begin{pmatrix} -2 & 2 & 0 \\ -1 & 0 & 2 \\ 0 & -1 & 2 \end{pmatrix} \rightarrow \begin{pmatrix} -1 & 0 & 2 \\ 0 & -1 & 2 \\ 0 & 2 & -4 \end{pmatrix} \rightarrow \begin{pmatrix} -1 & 0 & 2 \\ 0 & -1 & 2 \\ 0 & 0 & 0 \end{pmatrix}$$

This means that z is free, $y = 2z$ and $x = 2z$, and the solutions to the linear system can be written in the form

$$\mathbf{x} = \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 2z \\ 2z \\ z \end{pmatrix} = z \begin{pmatrix} 2 \\ 2 \\ 1 \end{pmatrix} = z \cdot \mathbf{v}_1, \quad \text{with } \mathbf{v}_1 = \begin{pmatrix} 2 \\ 2 \\ 1 \end{pmatrix}$$

That is, the solutions are the vectors in $\text{span}(\mathbf{v}_1)$.

- (c) The eigenvalues of
- A
- are given by the characteristic equation
- $\det(A - \lambda I) = 0$
- , which becomes

$$\begin{vmatrix} -2 - \lambda & 2 & 0 \\ -1 & -\lambda & 2 \\ 0 & -1 & 2 - \lambda \end{vmatrix} = 0$$

This gives the equation

$$(-2 - \lambda)(-\lambda(2 - \lambda) + 2) - 2(-1)(2 - \lambda) = 0$$

which gives, after multiplication, that

$$(-2 - \lambda)(\lambda^2 - 2\lambda + 2) + 2(2 - \lambda) = -\lambda^3 = 0$$

The eigenvalues are therefore $\lambda = 0$ (with multiplicity three).

QUESTION 2.

- (a) The difference equation can be written
- $y_{t+2} - 3y_{t+1} + 2y_t = 0$
- and is second order linear. It has characteristic equation
- $r^2 - 3r + 2 = 0$
- , with solutions
- $r = 1$
- and
- $r = 2$
- . Therefore, the general solution is

$$y_t = C_1 \cdot 1^t + C_2 \cdot 2^t = C_1 + C_2 \cdot 2^t$$

The initial conditions are $y_0 = C_1 + C_2 = 1$ and $y_1 = C_1 + 2C_2 = 2$, which gives $C_2 = 1$ and $C_1 = 0$. The solution is therefore

$$y_t = 2^t$$

- (b) The differential equation $y' - y \ln t = y$ is both linear and separable since it can be written $y' = y(\ln t + 1)$. We solve it as a linear differential equation $y' - (\ln t + 1)y = 0$. Since

$$\int \ln t \, dt = t \ln t - t + C$$

(using integration by parts with $u' = 1$ and $v = \ln t$), it follows that

$$\int -(\ln t + 1) \, dt = -(t \ln t - t + t) + C = -t \ln t + C$$

and that $e^{-t \ln t}$ is an integrating factor (with $C = 0$). Therefore, the differential equation can be written $(y e^{-t \ln t})' = 0$, which gives

$$y e^{-t \ln t} = K \quad \Rightarrow \quad y = K e^{t \ln t}$$

We could also solve it as a separable differential equation

$$y' = y(\ln t + 1) \quad \Rightarrow \quad \frac{1}{y} \cdot y' = \ln t + 1 \quad \Rightarrow \quad \int \frac{1}{y} \, dy = \int \ln t + 1 \, dt$$

The integral on the right hand side is computed as shown above. This gives

$$\ln |y| = t \ln t + C \quad \Rightarrow \quad |y| = e^{t \ln t + C} \quad \Rightarrow \quad y = K e^{t \ln t}$$

with $K = \pm e^C$.

- (c) The differential equation $ye^{yt} + te^{yt}y' = 1$ is not separable or linear, and we try to solve it as an exact differential equation. We write it in the form $(ye^{yt} - 1) + (te^{yt})y' = 0$, and try to find a function $h = h(y, t)$ such that

$$h'_t = ye^{yt} - 1, \quad h'_y = te^{yt}$$

From the first equation, it follows that $h = e^{yt} - t + C(y)$, since the derivative $(e^u)'_t = e^u \cdot y$ when $u = yt$ and $u'_t = y$. We check the second equation, and compute

$$h'_y = (e^{yt} - t + C(y))'_y = te^{yt} + C'(y)$$

Therefore $h = e^{yt} - t + C(y)$ is a solution to both equations if $C'(y) = 0$, and the simplest solution to this is $C(y) = 0$. We therefore have that

$$h(y, t) = e^{yt} - t = K \quad \Rightarrow \quad e^{yt} = t + K$$

The initial condition $y(1) = \ln 2$ gives $2 = 1 + K$, or $K = 1$. Hence the solution is

$$yt = \ln(t + K) = \ln(t + 1) \quad \Rightarrow \quad y = \frac{\ln(t + 1)}{t}$$

QUESTION 3.

- (a) To find out if $f(x, y, z) = 5x^2 - 8xy - 4xz + 5y^2 - 4yz + 8z^2 + 1$ is convex, we compute its first order partial derivatives

$$f'_x = 10x - 8y - 4z, \quad f'_y = -8x + 10y - 4z, \quad f'_z = -4x - 4y + 16z$$

and its Hessian matrix

$$H(f) = \begin{pmatrix} 10 & -8 & -4 \\ -8 & 10 & -4 \\ -4 & -4 & 16 \end{pmatrix}$$

The leading principal minors are $D_1 = 10$, $D_2 = 36$ and $D_3 = 16 \cdot 36 + 4(-72) - 4(72) = 0$. We have used cofactor expansion along the last row to compute D_3 . We see that the Hessian $H(f)$ may be positive semidefinite, and we must check if all principal minors $\Delta_i \geq 0$ to verify this. We compute that $\Delta_1 = 10, 10, 16 > 0$, $\Delta_2 = 36, 144, 144 > 0$ and $\Delta_3 = 0$. Hence $H(f)$ is positive semidefinite, and f is convex.

- (b) The stationary points of f are the solutions of the first order conditions, given by

$$f'_x = 10x - 8y - 4z = 0, \quad f'_y = -8x + 10y - 4z = 0, \quad f'_z = -4x - 4y + 16z = 0$$

This is a linear system, and we solve it using Gaussian elimination:

$$\begin{pmatrix} 10 & -8 & -4 \\ -8 & 10 & -4 \\ -4 & -4 & 16 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & -4 \\ 0 & -18 & 36 \\ 0 & 18 & -36 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & -4 \\ 0 & -1 & 2 \\ 0 & 0 & 0 \end{pmatrix}$$

We have divided the last row by -4 , and moved it to the top row, to simplify computations. We see that z is a free variable, that $y = 2z$ and that $x = -y + 4z = -2z + 4z = 2z$. Therefore, there are infinitely many stationary points, given by $(x, y, z) = (2z, 2z, z)$.

- (c) The minimal value of f is $f = 1$ since f is convex and $(0, 0, 0)$ is one of its stationary points, with $f(0, 0, 0) = 1$. We have that $g(x, y, z) = w \ln(w)$ with $w = f(x, y, z) \geq 1$. We can therefore think of $g(x, y, z)$ as the composite function $h(f(x, y, z))$, where $h(w) = w \ln(w)$ is a function defined for $w \geq 1$. Since $h'(w) = 1 \ln(w) + w(1/w) = \ln(w) + 1 > 0$, it follows that h is a strictly increasing function, and the value of $g(x, y, z)$ is minimal when $f(x, y, z)$ is minimal. Therefore, the minimum value of $g(x, y, z)$ is $h(1) = 1 \cdot \ln(1) = 0$, and this value is attained when $f(x, y, z) = 1$; that is, for all the stationary points $(x, y, z) = (2z, 2z, z)$.

QUESTION 4.

- (a) The Lagrangian is $\mathcal{L} = 5x^2 - 8xy - 4xz + 5y^2 - 4yz + 8z^2 + 1 - \lambda(x + y - 4z)$. The first order conditions (FOC) are

$$\begin{aligned} \mathcal{L}'_x &= 10x - 8y - 4z - \lambda = 0 \\ \mathcal{L}'_y &= -8x + 10y - 4z - \lambda = 0 \\ \mathcal{L}'_z &= -4x - 4y + 16z + 4\lambda = 0 \end{aligned}$$

and the constraint (C) is given by $x + y - 4z = 8$. The Lagrange conditions therefore give a 4×4 linear system $A \cdot \mathbf{x} = \mathbf{b}$, with augmented matrix $(A|\mathbf{b})$, given by

$$\begin{pmatrix} 1 & 1 & -4 & 0 \\ 10 & -8 & -4 & -1 \\ -8 & 10 & -4 & -1 \\ -4 & -4 & 16 & 4 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \\ z \\ \lambda \end{pmatrix} = \begin{pmatrix} 8 \\ 0 \\ 0 \\ 0 \end{pmatrix} \Rightarrow (A|\mathbf{b}) = \left(\begin{array}{cccc|c} 1 & 1 & -4 & 0 & 8 \\ 10 & -8 & -4 & -1 & 0 \\ -8 & 10 & -4 & -1 & 0 \\ -4 & -4 & 16 & 4 & 0 \end{array} \right)$$

when the columns correspond to the variables x, y, z, λ and we write the constraint (C) first and then the first order conditions (FOC).

- (b) We use Gaussian elimination to solve the Lagrange conditions, given by the linear system given in a):

$$\left(\begin{array}{cccc|c} 1 & 1 & -4 & 0 & 8 \\ 10 & -8 & -4 & -1 & 0 \\ -8 & 10 & -4 & -1 & 0 \\ -4 & -4 & 16 & 4 & 0 \end{array} \right) \rightarrow \left(\begin{array}{cccc|c} 1 & 1 & -4 & 0 & 8 \\ 0 & -18 & 36 & -1 & -80 \\ 0 & 0 & 0 & -2 & -16 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right)$$

This shows that there are infinitely many solutions to the Lagrange conditions, with z free, with $\lambda = 8$, with $-18y = -36z + 8 - 80 = -36z - 72$ which gives $y = 2z + 4$, and with $x = -y + 4z + 8 = 4z + 8 - (2z + 4) = 2z + 4$. In other words, the solutions are

$$(x, y, z; \lambda) = (2z + 4, 2z + 4, z; 8)$$

for any value of z . We choose one of these points, for example the point $(4, 4, 0; 8)$ with $z = 0$, and use the SOC: The Lagrangian

$$\mathcal{L}(x, y, z; 8) = 5x^2 - 8xy - 4xz + 5y^2 - 4yz + 8z^2 - 8(x + y - 4z)$$

has the same Hessian matrix as f in Question 3a). It follows that \mathcal{L} is a convex function, and therefore $(4, 4, 0)$ is a minimum point with minimum value $f(4, 4, 0) = 33$. Any of the other solutions $(x, y, z) = (2z + 4, 2z + 4, z)$ of the Lagrange conditions is also a minimum point with $f(2z + 4, 2z + 4, z) = 33$, since it gives the same Lagrangian.

(c) We consider the Lagrange problem $\min f(x, y, z)$ subject to $x + y - 4z = a$. Its Lagrangian is

$$\mathcal{L} = 5x^2 - 8xy - 4xz + 5y^2 - 4yz + 8z^2 + 1 - \lambda(x + y - 4z - a)$$

and we see that there is a solution $(x^*(a), y^*(a), z^*(a); \lambda^*(a))$ of the Lagrange conditions for each value of a . In fact, we find such solutions by replacing the linear system in b) with the linear system

$$\left(\begin{array}{cccc|c} 1 & 1 & -4 & 0 & a \\ 10 & -8 & -4 & -1 & 0 \\ -8 & 10 & -4 & -1 & 0 \\ -4 & -4 & 16 & 4 & 0 \end{array} \right) \rightarrow \left(\begin{array}{cccc|c} 1 & 1 & -4 & 0 & a \\ 0 & -18 & 36 & -1 & -10a \\ 0 & 0 & 0 & -2 & -2a \\ 0 & 0 & 0 & 0 & 0 \end{array} \right)$$

and see that $(x^*(a), y^*(a), z^*(a); \lambda^*(a)) = (2z + a/2, 2z + a/2, z; a)$ are solutions for all values of z . By the SOC, these solutions are minima for all values of z since the Lagrangian

$$\mathcal{L} = 5x^2 - 8xy - 4xz + 5y^2 - 4yz + 8z^2 + 1 - a(x + y - 4z - a)$$

is a convex function (it has the same Hessian as the Lagrangian in b). This implies that we can use the envelope theorem

$$\frac{df^*(a)}{da} = \mathcal{L}'_a(x^*(a), y^*(a), z^*(a); \lambda^*(a))$$

The right hand side is equal to $\lambda^*(a) = a$ since $\mathcal{L}'_a = \lambda$, and it follows that $df^*(a)/da = 8$ at $a = 8$. We estimate the new minimal value at $a = 7.92$ as

$$f^*(7.92) \cong f^*(8) + 8 \cdot \Delta a = 33 + 8 \cdot (-0.08) = 33 - 0.64 = 32.36$$

One finds that the exact value is $f^*(a) = f(x^*(a), y^*(a), z^*(a); \lambda^*(a)) = 1 + a^2/2$, which gives $f^*(7.92) = 32.3632$ is the exact solution to the new Lagrange problem.

QUESTION 5.

To compute the rank, we first find the determinant, and use cofactor expansion along the first row:

$$|A| = \begin{vmatrix} -\alpha_2 & \alpha_1 & 0 \\ -\alpha_3 & 0 & \alpha_1 \\ 0 & -\alpha_3 & \alpha_2 \end{vmatrix} = -\alpha_2(\alpha_1\alpha_3) - \alpha_1(-\alpha_2\alpha_3) = 0$$

Since $\det(A) = 0$, this means that $\text{rk } A \leq 2$, and we see that $\text{rk } A = 0$ if $(\alpha_1, \alpha_2, \alpha_3) = (0, 0, 0)$. When $(\alpha_1, \alpha_2, \alpha_3) \neq (0, 0, 0)$, we compute 2-minors to see if $\text{rk } A = 2$. Among the 2-minors, we look at

$$M_{12,23} = \begin{vmatrix} \alpha_1 & 0 \\ 0 & \alpha_1 \end{vmatrix} = \alpha_1^2, \quad M_{13,13} = \begin{vmatrix} -\alpha_2 & 0 \\ 0 & \alpha_2 \end{vmatrix} = -\alpha_2^2, \quad M_{23,12} = \begin{vmatrix} -\alpha_3 & 0 \\ 0 & -\alpha_3 \end{vmatrix} = \alpha_3^2$$

and notice that if $(\alpha_1, \alpha_2, \alpha_3) \neq (0, 0, 0)$, then at least one of these minors are non-zero, since at least one $\alpha_i \neq 0$. This means that $\text{rk } A = 2$ when $(\alpha_1, \alpha_2, \alpha_3) \neq (0, 0, 0)$. We get

$$\text{rk } A = \begin{cases} 2, & (\alpha_1, \alpha_2, \alpha_3) \neq (0, 0, 0) \\ 0, & (\alpha_1, \alpha_2, \alpha_3) = (0, 0, 0) \end{cases}$$