

LECTURE 6

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SEP 29, 2016

GKA 6035

MATHEMATICS

Plan:

- ① Review: Determinants of quadratic forms
- ② Unconstrained optimization
- ③ Convex and concave functions

Reading:

[ME3] 14.1-14.4,
14.8, 17.1-17.5

Midterm exam: Next Friday

Lecture 1-6

Tue at 17-20:
(next week)

Please tell me if there are
problems you want me to do.

Workbook 1-6 + Exam problems

① Reviews:

Ex: $Q(x_1, x_2, x_3, x_4) = -x_1^2 + 4x_1x_2 + 3x_1x_3 - 5x_2^2 - 6x_3^2 - x_4^2$

$$A = \begin{pmatrix} -1 & 2 & 3/2 & 0 \\ 2 & -5 & 0 & 0 \\ 3/2 & 0 & -6 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix}$$

4x4, symmetric

① Defn: $Q(x) = x^t \cdot A \cdot x$

② Signs of eigenvalues of A: $\lambda_1, \dots, \lambda_4$.

③ Principal minors of A and their signs

$$\begin{cases} D_1 = -1 < 0 \\ D_2 = 5 - 4 = 1 > 0 \\ D_3 = 9/2 \cdot 15/2 + (-6) \cdot 1 = 45/4 - 6 = 21/4 > 0 \\ D_4 = -1 \cdot 21/4 = -21/4 < 0 \end{cases}$$

Indefinite →

leading
principal
minors

Criterion:

Main { $D_1, D_2, D_3, \dots, D_n > 0 \iff Q$ positive definite
 $D_1, D_3, D_5, \dots < 0$ and
 $D_2, D_4, \dots > 0 \iff Q$ negative definite

Next { $\Delta_1, \Delta_2, \dots, \Delta_n \geq 0$
for all principal minors } $\iff Q$ positive
Semidefinite
 $\Delta_1, \Delta_3, \Delta_5, \dots \leq 0$
 $\Delta_2, \Delta_4, \Delta_6, \dots \geq 0$
for all principal minors } $\iff Q$ negative
Semidefinite
all other cases $\iff Q$ indefinite

Typical examples:

$D_2 < 0$ ($D_4 < 0, D_6 < 0, \dots$) $\implies Q$ indefinite

D_1 and D_3 have opposite signs $\implies Q$ indefinite

(Or two odd order principal minors)

② Unconstrained optimization

Functions in one and two variables
Calculus (derivatives)
Max/min

FORK1003: Lection 4-6
[MET]: First chapters

$f(x_1, x_2, x_3, \dots, x_n) = f(\underline{x})$
function in many variables

$$\underline{x} = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}$$

Unconstrained optimization:

$$\max / \min f(\underline{x}) = f(x_1, \dots, x_n)$$

Ex: $f(x, y, z) = \underbrace{x^2 + y^2 - 3yz + z^2}_{\text{quadratic form}} - \underbrace{2x + y - z}_{\text{degree 1 linear form}} + \underbrace{1}_{\text{constant}}$

Partial derivatives:

$$\frac{\partial f}{\partial x} = f'_x = \underline{2x - 2}$$

$$\frac{\partial f}{\partial y} = f'_y = \underline{2y - 3z + 1}$$

$$\frac{\partial f}{\partial z} = f'_z = \underline{-3y + 2z - 1}$$

first order partial derivatives

$$H(f) = \begin{pmatrix} 2 & 0 & 0 \\ 0 & 2 & -3 \\ 0 & -3 & 2 \end{pmatrix}$$

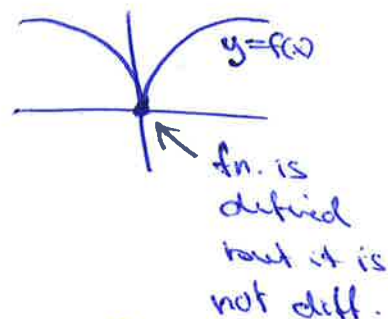
Hessian matrix of f
(second order partial derivatives)

$$H(f) = \begin{pmatrix} f''_{xx} & f''_{xy} & f''_{xz} \\ f''_{yx} & f''_{yy} & f''_{yz} \\ f''_{zx} & f''_{zy} & f''_{zz} \end{pmatrix}$$

Defn:

f is called a C^2 -function if all the second order partial derivatives of f exist and are continuous.

Ex: $f(x) = x^{2/3} = \sqrt[3]{x^2}, x \geq 0$
 $f'(x) = \frac{2}{3} x^{-1/3} = \frac{2}{3\sqrt[3]{x}}, x \neq 0$



$f(0) = 0$
 $f'(0)$ is not defined

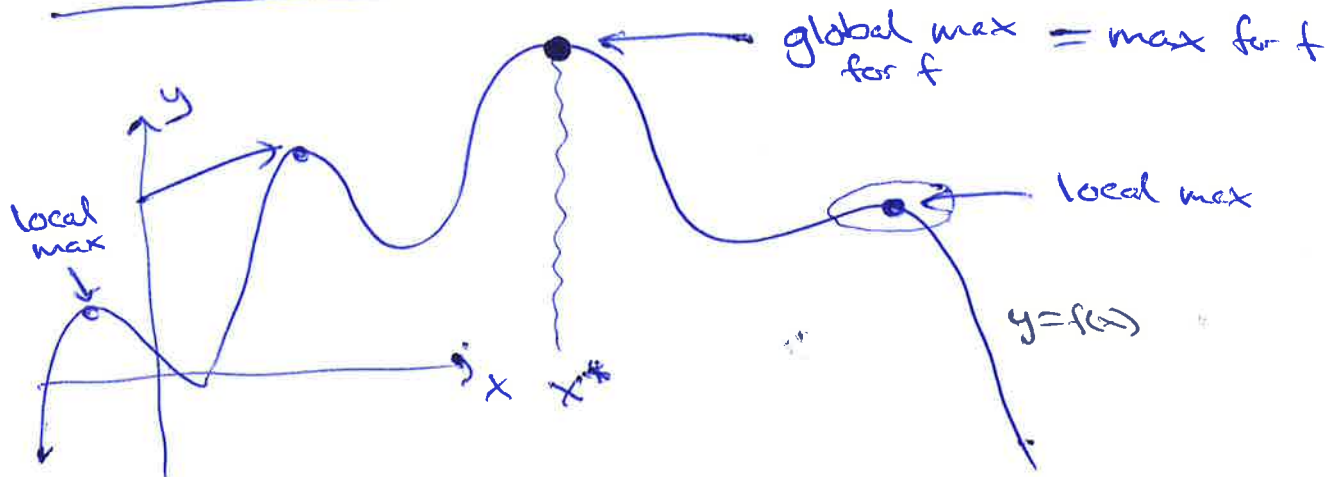
We only consider C^2 -functions in this course

Fact: $H(f)$ is symmetric (when f is C^2)

$$H(f) = \begin{pmatrix} f''_{11} & f''_{12} & \dots & f''_{1n} \\ f''_{21} & f''_{22} & \dots & f''_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ f''_{n1} & f''_{n2} & \dots & f''_{nn} \end{pmatrix} \text{ is symmetric} \iff f''_{ij} = f''_{ji}$$

Ex: $H(f) = \begin{pmatrix} 2 & 0 & 0 \\ 0 & 2 & -3 \\ 0 & -3 & 2 \end{pmatrix}$

Local/global max/min for $f(x)$



$$\begin{aligned} \underline{x^*} \quad & \text{global max} = \max \text{ for } f : f(x^*) \geq f(x) \text{ for all } x \text{ in } D_f \\ & \text{global min} = \min \quad \quad \quad f(x^*) \leq f(x) \quad \quad \quad \leftarrow \text{''} \end{aligned}$$

$$\begin{aligned} \underline{x^*} \quad & \text{local max for } f : f(x^*) \geq f(x) \text{ for all } x \text{ nearby} \\ & \text{local min} \quad \quad \quad f(x^*) \leq f(x) \quad \quad \quad \leftarrow \text{''} \end{aligned}$$

Method for finding unconstrained global max/min

$f(x_1, \dots, x_n) = f(x)$:

Ex: $f(x,y) = x^3 + 3xy - y^3$

Defn: A stationary point for f is a point where

$$f'_{x_1} = f'_{x_2} = \dots = f'_{x_n} = 0$$

$$f'_x = 3x^2 + 3y = 0$$

$$f'_y = 3x - 3y^2 = 0$$

FOC = first order conditions

$$f'_x = 3x^2 + 3y = 0$$

$$f'_y = 3x - 3y^2 = 0$$

$$x^2 + y = 0$$

$$x - y^2 = 0 \Rightarrow x = y^2$$

$$(y^2)^2 + y = 0$$

$$y^4 + y = 0$$

$$y(y^3 + 1) = 0$$

$$\frac{y=0}{x=0} \quad \text{or} \quad \frac{x=-1}{x=1} = \sqrt[3]{-1}$$

Stationary pts

$$(x,y) = (0,0)$$

$$(1,-1)$$

candidates for max/min

Fact:

If \underline{x}^* is a max/min for f , then it is a stationary pt.

$$\underline{x}^* \text{ max/min for } f \Rightarrow \underline{x}^* \text{ stationary pt.}$$

Classify stationary pts as local max, local min, saddle pt.

Defn: Saddle pt = stationary pt that is not local max and not local min.

Fact: Second derivative test

Look at $H(f)(\underline{x}^*)$ for a stationary pt. \underline{x}^* .

$H(f)(\underline{x}^*)$ pos. definite $\Rightarrow \underline{x}^*$ local min

$H(f)(\underline{x}^*)$ neg. definite $\Rightarrow \underline{x}^*$ local max

$H(f)(\underline{x}^*)$ indefinite $\Rightarrow \underline{x}^*$ saddle pt

Otherwise, the test is inconclusive.

Ex: $f = x^3 + 3xy - y^3$

$$f'_x = 3x^2 + 3y$$

$$f'_y = 3x - 3y^2$$

Stationary pts:

$$(x,y) = (0,0) \\ (1,-1)$$

$$f(1,-1) = -1 \quad f(0,2) = -8$$

$$H(f)(x,y) = \begin{pmatrix} 6x & 3 \\ 3 & -6y \end{pmatrix}$$

At (0,0):

$$H(f)(0,0) = \begin{pmatrix} 0 & 3 \\ 3 & 0 \end{pmatrix} = \begin{pmatrix} A & B \\ B & C \end{pmatrix}$$

$$\left. \begin{aligned} A &= D_1 = 0 \\ AC - B^2 &= D_2 = -9 \end{aligned} \right\} \text{indefinite}$$

$$\left(\begin{aligned} &A > 0, AC - B^2 > 0 : \text{local min} \\ &D_1, D_2 \end{aligned} \right)$$

(0,0) saddle pt

At (1,-1):

$$H(f)(1,-1) = \begin{pmatrix} 6 & 3 \\ 3 & 6 \end{pmatrix}$$

$$\left. \begin{aligned} D_1 &= 6 \\ D_2 &= 36 - 9 = 27 \end{aligned} \right\} \begin{array}{l} \text{pos.} \\ \text{definite} \end{array}$$

(1,-1) local min

||

Conclusion:

No max.

Candidate for min: (1,-1)

$$f(1,-1) = -1$$

No global min since $f(0,2) = -8 < f(1,-1) = -1$

Method:

- Find all stationary pts

$$f'_{x_1} = f'_{x_2} = \dots = f'_{x_n} = 0$$

- Classify them as local max/min, saddle pt.

$$H(f)(x^*)$$

An Example

Let $f(x,y) = x^2y^3 + y^2 - 2y$. Then f has just one stationary pt, which is a local min. However, f has no global min.

$$f'_x = 2xy^3 = 0$$

$$f'_y = 3x^2y^2 + 2y - 2 = 0$$

FOC: ~~2~~ $x=0$ or $y=0$

If $x=0$, then (2) gives

$$2y - 2 = 0 \Rightarrow y = 1$$

If $y=0$, then (2) gives

$$-2 = 0 \quad \text{no solution}$$

$$H(f) = \begin{pmatrix} 2y^3 & 6xy^2 \\ 6xy^2 & 6x^2y + 2 \end{pmatrix}$$

$$H(f)(0,1) = \begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix} \quad D_1 = 2 > 0$$

$$D_2 = 4 > 0$$

pos. detn. \Rightarrow $(0,1)$ local min

Conclusion: $(0,1)$ is the only stationary pt, with $f(0,1) = -1$

But $(x,y) = (0,1)$ with $f(0,1) = -1$ is not global min

For example,

$$f(3,-1) = -9 + 1 + 2 = -6 < -1$$

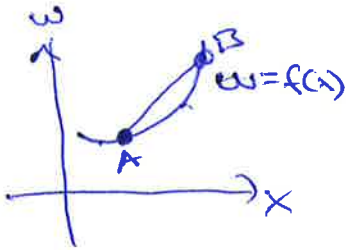
Conclusion: f has no global min even if $(0,1)$ is local min and this is the only stationary point.

3 Convex / concave functions

Defn: $f(x_1, \dots, x_n)$ is convex



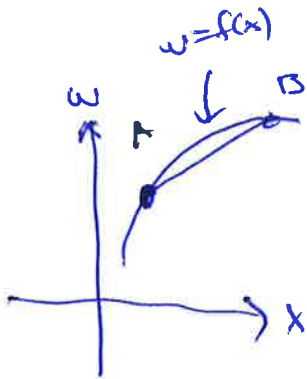
For any pts A and B on the graph of f , the line segment $[A, B]$ lies over the graph of f (or on the graph)



$f(x_1, \dots, x_n)$ is concave



For any pts A and B on the graph of f , the line segment $[A, B]$ lies under the graph of f (or on the graph)



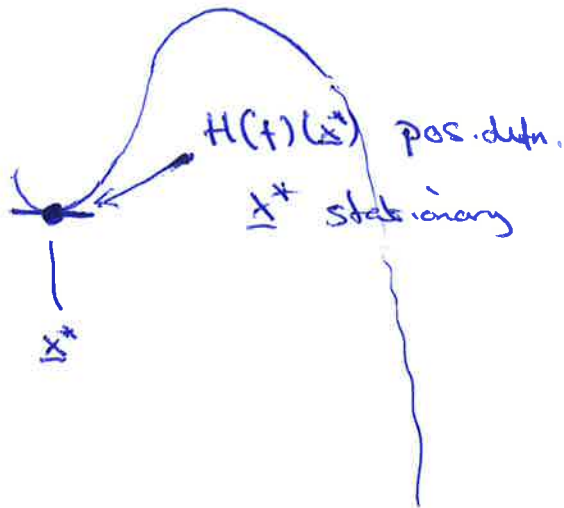
Test:

f convex $\iff H(f)$ is positive semidefinite
for all x in D_f .

f concave $\iff H(f)$ is negative semidefinite
for all x in D_f .

Result:

If f is convex, then any stationary pt is a global min.
If f is concave, then ——— is a global max.



$H(f)$
IS pos
semidefn.
at all
pts

Ex. $f = x^3 + 3xy - y^3$ convex/concave?

$$f'_x = 3x^2 + 3y$$

$$f'_y = 3x - 3y^2$$

$$\Rightarrow H(f) = \begin{pmatrix} 6x & 3 \\ 3 & -6y \end{pmatrix}$$

f convex

$$D_1 \geq 0 \text{ for all } (x,y)$$

$$6x \geq 0 \text{ for all } (x,y)$$

$$D_2 \geq 0 \quad \text{---} \text{---}$$

$$-36xy - 9 \geq 0 \quad \text{---} \text{---}$$

$$D_1 = 6x$$

$$D_2 = -36xy - 9$$

← not satisfied

f not convex

not concave

Ex. $f = e^{2x-y}$ is convex

$$f'_x = e^{2x-y} \cdot 2 = 2e^{2x-y}$$

$$f'_y = e^{2x-y} \cdot (-1) = -e^{2x-y}$$

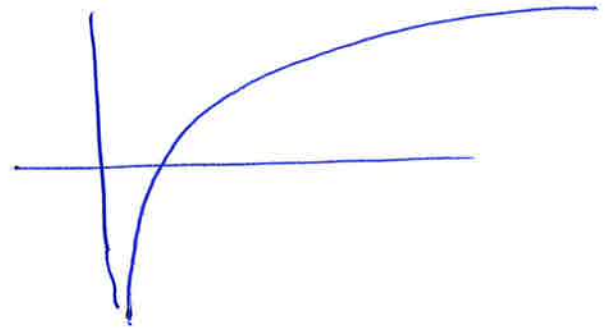
$$H(f) = \begin{pmatrix} \frac{4e^{2x-y}}{e^{2x-y}} & -2e^{2x-y} \\ -2e^{2x-y} & e^{2x-y} \end{pmatrix} = \begin{pmatrix} 4 & -2 \\ -2 & 1 \end{pmatrix} \cdot e^{2x-y}$$

$$D_1 = 4e^{2x-y} > 0 \text{ for all } x,y \quad \Delta_1 = D_1 \cdot e^{2x-y} > 0$$

$$D_2 = 4(e^{2x-y})^2 - 4(e^{2x-y})^2 = 0 \geq 0 \text{ for all } x,y$$

Not all convex/concave fn's have global max/min:

Ex: $f(x) = \ln(x), x > 0$
 $f'(x) = \frac{1}{x}$
 $f'' = -\frac{1}{x^2} < 0, x > 0$
Concave



no global max since
there is no stationary pt.

$$\left(\begin{array}{l} f' = \frac{1}{x} = 0 \\ \text{no solution} \end{array} \right)$$