

LECTURE 2

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GRA 6035

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MATHEMATICS

Plan:

- ① Matrices and matrix algebra
- ② Determinants
- ③ Minors, rank and linear algebra

Reading:

[HEJ] 8.1-8.4, (8.5-8.6), 9.1-9.2, (9.3), 26.1-26.3, (26.4), 26.5

① Matrices

An $m \times n$ -matrix A is a rectangular array of numbers with m rows ($\# \text{rows} = m$) and n columns ($\# \text{cols} = n$):

$$A = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{pmatrix} = (a_{ij})$$

the number
in the matrix A
in pos. $(1,2)$
↑ ↑
row col.

Ex: $A = \begin{pmatrix} 2 & 3 & 1 \\ -1 & 7 & 4 \end{pmatrix}$

2×3 -matrix

Matrix Operations

i) Addition / Subtraction $A + B, A - B$

- defined when A, B have the same size
 - computed pos. by pos.

$$\begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} + \begin{pmatrix} -1 & 2 \\ 3 & -2 \end{pmatrix} = \underline{\underline{\begin{pmatrix} 0 & 4 \\ 6 & 2 \end{pmatrix}}}$$

Zero matrix:

$$O_{2 \times 2} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} = 0$$

ii) Multiplication $A \cdot B$

- defined when $\# \text{ cols in } A = \# \text{ rows in } B$

Ex: $\begin{pmatrix} 1 & -1 \\ 2 & 0 \end{pmatrix} \cdot \begin{pmatrix} 3 & 2 & 7 \\ 1 & 4 & 1 \end{pmatrix} = \begin{pmatrix} 2 & -2 & 6 \\ 6 & 4 & 14 \end{pmatrix}$

2×2 2×3 2×3

$$1 \cdot 3 + (-1) \cdot 1 = 2$$

Not symmetric: $A \cdot B \neq B \cdot A$ (in general)

Ex: $\begin{pmatrix} 3 & 2 & 7 \\ 1 & 4 & 1 \end{pmatrix} \cdot \begin{pmatrix} 1 & -1 \\ 2 & 0 \end{pmatrix}$ is not defined

$2 \times 3 \neq 2 \times 2$

Identity matrix:

$$I_n = \begin{pmatrix} 1 & 0 & 0 & \dots & 0 \\ 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 1 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & 1 \end{pmatrix} = I$$

(n x n identity matrix)

$$I_2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

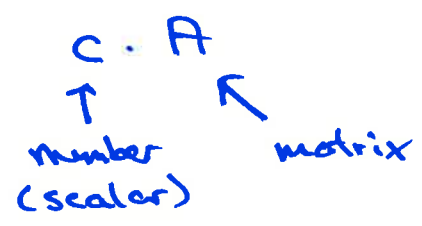
$$I_3 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

It has the property that :

$$\begin{matrix} A \cdot I = A \\ I \cdot B = B \end{matrix}$$

Ex: $\begin{pmatrix} 1 & 2 \\ 4 & -1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 2 \\ 4 & -1 \end{pmatrix}$

iii) Scalar multiplication



Ex: $2 \cdot \begin{pmatrix} 1 & 2 \\ 4 & -1 \end{pmatrix}$
 $= \begin{pmatrix} 2 & 4 \\ 8 & -2 \end{pmatrix}$

← in the example

$$c \cdot A = c \cdot I \cdot A = (cI) \cdot A = \begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix} \cdot \begin{pmatrix} 1 & 2 \\ 4 & -1 \end{pmatrix}$$

$$= \begin{pmatrix} 2 & 4 \\ 8 & -2 \end{pmatrix}$$

Consequence: $C \cdot A = A \cdot C$
 $(CI) \cdot A = A \cdot (CI)$

Algebraic laws for matrices

Ex: $A \cdot (B+C) = AB + AC$
 $A+B = B+A$

But: $AB \neq BA$

Ex: $(A+B)(A-B) = A \cdot A + B \cdot A - A \cdot B - B \cdot B$
 $= A^2 + BA - AB - B^2$

Ex: $A = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$ $B = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$

$$A \cdot B = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \neq B \cdot A = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

$$C = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} : A \cdot C = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

iv) Transpose: $A^T = A^t$

Ex: $A = \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix} \longrightarrow A^T = \begin{pmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{pmatrix}$
 2×3 3×2

$A = \begin{pmatrix} 1 & 2 \\ 2 & 3 \end{pmatrix} \longrightarrow A^T = \begin{pmatrix} 1 & 2 \\ 2 & 3 \end{pmatrix}$

A is called a symmetric matrix if $A^T = A$.

This is the same as to say that $a_{ij} = a_{ji}$ for all $i \neq j$.

Ex: $A = \begin{pmatrix} 2 & 4 & 2 \\ 4 & 3 & 7 \\ 2 & 7 & -1 \end{pmatrix}$ is symmetric

Properties of the transpose:

$$i) (A^T)^T = A$$

$$ii) (A \cdot B)^T = B^T \cdot A^T$$

Square matrices: A is square if #rows in A = #cols in A

When A is square, then A^2, A^3, A^4, \dots is defined

$$A^2 = A \cdot A$$

$$A^3 = A \cdot A \cdot A$$

$$\vdots$$

Ex: $A = \begin{pmatrix} 2 & 1 \\ -1 & 0 \end{pmatrix}$

$$A^2 = \begin{pmatrix} 2 & 1 \\ -1 & 0 \end{pmatrix} \cdot \begin{pmatrix} 2 & 1 \\ -1 & 0 \end{pmatrix} = \begin{pmatrix} 4-1 & 2+0 \\ -2+0 & -1+0 \end{pmatrix} = \begin{pmatrix} 3 & 2 \\ -2 & -1 \end{pmatrix}$$

$$A^3 = A \cdot A^2 = \begin{pmatrix} 2 & 1 \\ -1 & 0 \end{pmatrix} \cdot \begin{pmatrix} 3 & 2 \\ -2 & -1 \end{pmatrix} = \begin{pmatrix} 4 & 3 \\ -3 & -2 \end{pmatrix}$$

it is possible but difficult to compute

$$A^{100}, A^n$$

v) Inverse matrices

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A matrix A is said to have an inverse matrix if there is a matrix A^{-1} such that

$$A \cdot A^{-1} = I$$

$$A^{-1} \cdot A = I$$

Ex:

$$3^{-1} = \frac{1}{3}$$

$$3 \cdot \frac{1}{3} = 1$$

Ex: $A = \begin{pmatrix} 3 & 1 \\ 2 & 1 \end{pmatrix}$ $A^{-1} = \frac{1}{1} \cdot \begin{pmatrix} 1 & -1 \\ -2 & 3 \end{pmatrix} = \begin{pmatrix} 1 & -1 \\ -2 & 3 \end{pmatrix}$

$$\begin{pmatrix} 3 & 1 \\ 2 & 1 \end{pmatrix} \cdot \begin{pmatrix} 1 & -1 \\ -2 & 3 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & -1 \\ -2 & 3 \end{pmatrix} \cdot \begin{pmatrix} 3 & 1 \\ 2 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

Facts:

- If the inverse exists, it is unique
- For the inverse to exist, A must be square and $|A| \neq 0$. Then A is called invertible.

The case: $n=2$

$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

$$|A| = ad - bc$$

$$|A| \neq 0: \quad A^{-1} = \frac{1}{ad-bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$$

$|A| = 0: \quad A^{-1}$ does not exist

Remember:

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A invertible \iff A is square with $|A| \neq 0$

Ex: Linear systems in matrix form

$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1$$

⋮

$$a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m$$

$m \times n$ linear system

$$A = (a_{ij}) \quad \text{coeff. matrix}$$

$$\hat{A} = (A \mid \underline{b}) \quad \text{aug. matrix}$$

$$\underline{b} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{pmatrix}$$

The same linear system can be written in matrix form:

$$\underline{A} \cdot \underline{x} = \underline{b}$$

A: coeff. matrix

$$\underline{x} = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} \quad \underline{b} = \begin{pmatrix} b_1 \\ \vdots \\ b_m \end{pmatrix}$$

Ex:

$$\begin{aligned} x + y &= 4 \\ x - y &= 2 \end{aligned}$$

$$A = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \quad \underline{x} = \begin{pmatrix} x \\ y \end{pmatrix} \quad \underline{b} = \begin{pmatrix} 4 \\ 2 \end{pmatrix}$$

$$\underline{A} \cdot \underline{x} = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x+y \\ x-y \end{pmatrix} \quad \underline{b} = \begin{pmatrix} 4 \\ 2 \end{pmatrix}$$

$$\underline{A} \underline{x} = \underline{b} \iff$$

$$\begin{cases} x+y=4 \\ x-y=2 \end{cases}$$

$$\underline{A}^{-1}(\underline{A} \underline{x}) = \underline{A}^{-1} \cdot \underline{b}$$

$$\underline{x} = \underline{A}^{-1} \underline{b} = \frac{1}{-2} \cdot \begin{pmatrix} -1 & -1 \\ -1 & 1 \end{pmatrix} \cdot \begin{pmatrix} 4 \\ 2 \end{pmatrix} = \underline{\underline{\begin{pmatrix} 3 \\ 1 \end{pmatrix}}}$$

② Determinants

$$A = (a_{ij}) \rightsquigarrow \det(A) = |A|$$

$n \times n$ -matrix

determinant of
 A , it is a
number

$n=2$:

$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \rightsquigarrow |A| = ad - bc$$

$n=3$:

$$A = \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix}$$

only works
for $n=3$

$$|A| = aei + bfg + cdh \\ - ceg - afh - bdi$$

Ex: $A = \begin{pmatrix} 1 & 1 & 1 \\ 1 & -1 & 1 \\ 1 & 2 & 4 \end{pmatrix}$

$$|A| = -4 + 1 + 2 \\ - (-1) - 2 - 4 = \underline{\underline{-6}}$$

In general: $\begin{cases} - \text{Cofactor expansion} \\ - \text{Gaussian elimination} \end{cases}$
 (works for any n)

i) Cofactor expansion

$$A = \begin{pmatrix} a_{11} & a_{12} & a_{13} & \dots & a_{1n} \\ \vdots & \vdots & \vdots & & \vdots \\ \vdots & \vdots & \vdots & & \vdots \\ \vdots & \vdots & \vdots & & \vdots \end{pmatrix}$$

$n \times n$ -matrix

← along the first row

$$|A| = a_{11} \cdot C_{11} + a_{12} \cdot C_{12} + \dots + a_{1n} \cdot C_{1n}$$

C_{ij} : the cofactor in position (i,j)

$$C_{ij} = \underbrace{(-1)^{i+j}}_{\text{sign}} \cdot \underbrace{M_{ij}}_{\text{minor}}$$

M_{ij} : minor in position (i,j)

M_{ij} = determinant of the submatrix you get when you delete row $\neq i$, col $\neq j$.

Ex:

$$A = \begin{pmatrix} 1 & 1 & 1 \\ -1 & 1 & 1 \\ 2 & 4 & 1 \end{pmatrix}$$

Signs:

$$\begin{pmatrix} + & - & + \\ - & + & - \\ + & - & + \end{pmatrix}$$

$$\begin{aligned} |A| &= 1 \cdot (+1) \cdot M_{11} + 1 \cdot (-1) \cdot M_{12} + 1 \cdot (+1) \cdot M_{13} \\ &= + \begin{vmatrix} -1 & 1 \\ 2 & 4 \end{vmatrix} - \begin{vmatrix} 1 & 1 \\ 2 & 4 \end{vmatrix} + \begin{vmatrix} 1 & -1 \\ -1 & 1 \end{vmatrix} \\ &= -6 - 3 + 3 = \underline{\underline{-6}} \end{aligned}$$

Facts:

- i) Cofactor expansion works for any $n \times n$ -matrix
- ii) Cofactor expansion along any row or column gives the same result.

Ex:

$$A = \begin{pmatrix} 1 & 2 & 4 \\ 0 & 7 & 5 \\ 0 & 0 & 13 \end{pmatrix}$$

$$\begin{aligned} |A| &= +1 \cdot \begin{vmatrix} 7 & 5 \\ 0 & 13 \end{vmatrix} - 0 \dots + 0 \dots \\ &= 1 \cdot 7 \cdot 13 = \underline{\underline{91}} \end{aligned}$$

Fact:

A is called upper triangular if it is square with only zeros under the diagonal,
 $a_{ij} = 0$ when $i > j$

$$A = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ 0 & a_{22} & \dots & a_{2n} \\ 0 & 0 & \dots & \dots \\ \vdots & \vdots & \dots & \vdots \\ 0 & 0 & \dots & a_{nn} \end{pmatrix}$$

If A is upper triangular, then

$$|A| = a_{11} \cdot a_{22} \cdot \dots \cdot a_{nn}$$

(i) Determinants via Gaussian elimination

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Ex: $A = \begin{pmatrix} 1 & 1 & 1 \\ 1 & -1 & 1 \\ 1 & 2 & 4 \end{pmatrix} \begin{matrix} \leftarrow -1 \\ \leftarrow -1 \end{matrix}$ $|A| = |E| = \underline{\underline{-6}}$

↓

$$\begin{pmatrix} 1 & 1 & 1 \\ 0 & -2 & 0 \\ 0 & 1 & 3 \end{pmatrix} \begin{matrix} \leftarrow \frac{1}{2} \\ \leftarrow (-2) \end{matrix} \rightarrow \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 0 \\ 0 & 1 & 3 \end{pmatrix} \begin{matrix} \leftarrow -1 \\ \leftarrow -1 \end{matrix} \rightarrow \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 3 \end{pmatrix}$$

↓

$|E| = 3$
 $\frac{|A|}{-2} = |E| = 3 \Rightarrow |A| = -6$

echelon
form,
upper
triangular

$$E = \begin{pmatrix} 1 & 1 & 1 \\ 0 & -2 & 0 \\ 0 & 0 & 3 \end{pmatrix}$$

$$|E| = 1 \cdot (-2) \cdot 3 = \underline{\underline{-6}}$$

Elementary row operations:

- If you add a multiple of one row to another row, the determinant does not change.
- If you switch two rows, the determinant changes with a factor of -1.
- If you multiply a row with $c \neq 0$, then the determinant changes with a factor of c.

Properties of the determinant

$$i) |AB| = |A| \cdot |B|$$

$$ii) |A^T| = |A|$$

$$iii) |A^{-1}| = \frac{1}{|A|}$$

$$iv) |cA| = c^n \cdot |A| \quad \text{when } c \text{ is a number,} \\ A \text{ is } n \times n \text{-matrix}$$

Exercise:

Compute

$$\begin{vmatrix} 4 & 0 & 0 & -1 & -1 \\ 0 & 2 & 0 & 1 & -1 \\ 0 & 0 & 6 & -2 & 0 \\ 1 & -1 & 2 & 0 & 0 \\ 1 & 1 & 0 & 0 & 0 \end{vmatrix}$$

Sol:

$$\begin{vmatrix} 4 & 0 & 0 & -1 & -1 \\ 0 & 2 & 0 & 1 & -1 \\ 0 & 0 & 6 & -2 & 0 \\ 1 & -1 & 2 & 0 & 0 \\ 1 & 1 & 0 & 0 & 0 \end{vmatrix} \begin{matrix} \leftarrow \\ \leftarrow \\ \leftarrow \\ \leftarrow \\ \leftarrow \end{matrix} \begin{matrix} -1 \\ -1 \\ -1/4 \\ -1/4 \end{matrix}$$

$$= \begin{vmatrix} 4 & 0 & 0 & -1 & -1 \\ 0 & 2 & 0 & 1 & -1 \\ 0 & 0 & 6 & -2 & 0 \\ 0 & -1 & 2 & 1/4 & 1/4 \\ 0 & 1 & 0 & 1/4 & 1/4 \end{vmatrix}$$

$$= 4 \begin{vmatrix} 2 & 0 & 1 & -1 \\ 0 & 6 & -2 & 0 \\ -1 & 2 & 1/4 & 1/4 \\ 1 & 0 & 1/4 & 1/4 \end{vmatrix} \begin{matrix} \leftarrow \\ \leftarrow \\ \leftarrow \\ \leftarrow \end{matrix} \begin{matrix} -2 \\ -2 \\ 1 \\ 1 \end{matrix}$$

$$= 4 \cdot \begin{vmatrix} 0 & 1/2 & -3/2 \\ 0 & 6 & -2 \\ 0 & 2 & 1/2 \\ 1 & 0 & 1/4 \end{vmatrix}$$

$$= 4 \cdot 1 \cdot (-1) \cdot \begin{vmatrix} 0 & 1/2 & -3/2 \\ 6 & -2 & 0 \\ 2 & 1/2 & 1/2 \end{vmatrix}$$

$$= -4 \cdot \left(-6 \cdot \left(\frac{1}{4} + \frac{3}{4} \right) + 2(-3) \right)$$

$$= -4 \cdot (-6 - 6) = -4 \cdot (-12) = \underline{\underline{48}}$$

③ Minors and rank

A
m x n
matrix

A minor of order r in A is the determinant of an $r \times r$ submatrix of A .

Ex: $A = \begin{pmatrix} 1 & 2 & 4 \\ 7 & -1 & 3 \end{pmatrix}$
2 x 3

Order 2 minors: Delete one column

$$M_{12,12} = \begin{vmatrix} 1 & 2 \\ 7 & -1 \end{vmatrix} = -15$$

$$M_{12,13} = \begin{vmatrix} 1 & 4 \\ 7 & 3 \end{vmatrix} = -25$$

$$M_{12,23} = \begin{vmatrix} 2 & 4 \\ -1 & 3 \end{vmatrix} = 10$$

Order 1 minors:

$$M_{1,1} = \underline{1} \quad M_{1,2} = \underline{2} \quad M_{1,3} = \underline{4}$$

$$M_{2,1} = \underline{7} \quad M_{2,2} = \underline{-1} \quad M_{2,3} = \underline{3}$$

Since we have a 2-minor that is non-zero, the rank of A is 2.
(2-minor = max. minor)

Fact:

The rank of a matrix is equal to the maximal order of a non-zero minor.

Ex: Minors and linear systems

$$x + y + z + w = 4$$

$$x + 2y + 3z - w = 2$$

$$x + 3y + z = 1$$

$$A = \begin{pmatrix} 1 & 1 & 1 & 1 \\ 1 & 2 & 3 & -1 \\ 1 & 3 & 1 & 0 \end{pmatrix}$$

$$\hat{A} = \left(\begin{array}{cccc|c} 1 & 1 & 1 & 1 & 4 \\ 1 & 2 & 3 & -1 & 2 \\ 1 & 3 & 1 & 0 & 1 \end{array} \right)$$

↑
w
free

Maximal minors

$$\begin{vmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \\ 1 & 3 & 1 \end{vmatrix} = 1 \cdot (-2) - 1 \cdot (-2) + 1 \cdot 1 = -4 \neq 0$$

∥

- rank is 3
- the pivot positions are inside this submatrix
- w is a free variable inf. many solutions

Solution:

w is free, move to the other side

$$x + y + z = 4 - w$$

$$x + 2y + 3z = 2 + w$$

$$x + 3y + z = 1$$

matrix corresponds to non-zero minor, so its determinant is non-zero and the inverse exists

$$\begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \\ 1 & 3 & 1 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 4-w \\ 2+w \\ 1 \end{pmatrix} \Rightarrow \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \\ 1 & 3 & 1 \end{pmatrix}^{-1} \cdot \begin{pmatrix} 4-w \\ 2+w \\ 1 \end{pmatrix}$$

When we solve a linear system using minors:

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Assume that $\text{rk } A = \text{rk } \hat{A} = r$, and choose a non-zero minor in A of order r .

- * Look at the r equations "running through" the minor chosen, and ignore the rest.
- * Solve these equations for the variables "in the minor", the rest are free variables.

$$\begin{aligned}x + y + z + w &= 4 \\x - 2y + 3z - w &= 2 \\x + 3y - z &= 1\end{aligned}$$

$$A = \begin{pmatrix} 1 & 1 & 1 & 1 \\ 1 & -2 & 3 & -1 \\ 1 & 3 & -1 & 0 \end{pmatrix}$$

$$\begin{vmatrix} 1 & 1 & 1 \\ 1 & -2 & 3 \\ 1 & 3 & -1 \end{vmatrix} = -4 \neq 0$$

maximal non-zero minor

$$\begin{aligned}x + y + z &= 4 - w \\x - 2y + 3z &= 2 + w \\x + 3y - z &= 1\end{aligned}$$

Use eqn. 1-3

Solve for x, y, z ; w is free

Solve for x, y, z



$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 & 1 & 1 \\ 1 & -2 & 3 \\ 1 & 3 & -1 \end{pmatrix}^{-1} \begin{pmatrix} 4 - w \\ 2 + w \\ 1 \end{pmatrix}$$