

LECTURE 14

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MATHEMATICS

Plan:

* Review (continued): Optimization, Differential equations

* Final Exam 12/2014: Question 3-4 (5)

A) Differential equations / Difference equations

Differential equations:

First order: $y' = F(y, t)$

a) Linear: $y' + a(t) \cdot y = f(t)$

Methods: Integrating factor
 $u = e^{\int a(t) dt}$

Multiplying with
int. factor:

$$(u(t) \cdot y)' = f(t) \cdot u(t)$$

$$y = \frac{1}{u(t)} \int f(t) \cdot u(t) dt$$

Works if \rightarrow
 $a(t) = a$
is a constant.

$$\begin{cases} y' + ay = 0 \\ r + a = 0 \\ r = -a \end{cases}$$

\rightarrow Superposition principle

$$y = y_h + y_p$$

$$= C \cdot e^{-at} + y_p$$

Second order:

Linear: $y'' + ay' + by = f(t)$

Method: Superposition
principle

$$y = y_h + y_p$$

y_h : $y'' + ay' + by = 0$

$$r^2 + ar + b = 0$$

Find y_h from
these roots:

$$r_1 \neq r_2: y_h = C_1 e^{r_1 t} + C_2 e^{r_2 t}$$

$$r_1 = r_2: y_h = C_1 e^{r_1 t} + C_2 t e^{r_2 t}$$

How to find yp: $y'' + ay' + by = f(t)$

Start with $f(t)$, compute f' (and maybe f'')
 Make a guess $y(t)$ based on the form of f, f', f'' with undetermined coeffs.
 Substitute y into the diff. eqn. and try to adjust the coeffs. to find a solution.
 If it doesn't work, try to multiply with t .

First order:

b) Separable: $y' = f(y) \cdot g(t)$

Method: $\int \frac{1}{f(y)} y' dt = \int g(t) dt$

$\int \frac{1}{f(y)} dy = \int g(t) dt$

c) Exact: $p(y,t) + q(y,t) \cdot y' = 0$ is exact if there is an $h = h(y,t)$ st.

Method: $\begin{cases} \frac{\partial h}{\partial t} + \frac{\partial h}{\partial y} \cdot \frac{dy}{dt} = 0 \\ \text{In that case:} \end{cases}$

$h(y,t) = C$

Difference equations

Linear first order: $y_{t+1} + ay_t = f_t$

Superposition principle:

$$y_t = y_t^h + y_t^p$$

$$= C \cdot (-a)^t + y_t^p$$

Linear second order:

$y_{t+2} + ay_{t+1} + by_t = f_t$

Method: $y_t = y_t^h + y_t^p$

Char. eqn: $r^2 + ar + b = 0$

$r_1 \neq r_2$: $y_t^h = C_1 \cdot r_1^t + C_2 \cdot r_2^t$

$r_1 = r_2$: $y_t^h = C_1 \cdot r_1^t + C_2 \cdot t \cdot r_1^t$

Question 3

a) $y_{t+1} - 3y_t = -5(2t+1) \leftarrow$

Difference eqn.
Linear first order

$y_t = y_t^h + y_t^p = \underline{\underline{C \cdot 3^t + 5t + 5}}$

y_t^h : $y_{t+1} - 3y_t = 0$

$r - 3 = 0 \quad \underline{r=3} \Rightarrow y_t^h = \underline{C \cdot 3^t}$

y_t^p : $y_{t+1} - 3y_t = -5(2t+1) = \underline{-10t - 5}$

$f_t = -10t - 5$

$f_{t+1} = -10(t+1) - 5 = -10t - 15$

Guess:

$y_t = \underline{At + B}$

$y_{t+1} = A \cdot (t+1) + B$
 $= \underline{At + A + B}$

$(At + A + B) - 3(At + B) = -10t - 5$

$\underline{(-2A)t} + \underline{(A - 2B)} = \underline{-10t - 5}$

$-2A = -10$

$A - 2B = -5$

$A = \underline{5}$

$5 - 2B = -5$

$-2B = -10$

$B = \underline{5}$

$\overset{p}{y}_t = \underline{At + B}$
 $= \underline{5t + 5}$

$$b) \quad t^3 y' = y^2$$

$$y' = \left(\frac{1}{t^3}\right) (y^2)$$

$$\frac{1}{y^2} y' = \frac{1}{t^3}$$

$$\int \frac{1}{y^2} y' dt = \int \frac{1}{t^3} dt$$

$$\int y^{-2} dy = \int t^{-3} dt$$

$$\frac{y^{-1}}{-1} = \frac{t^{-2}}{-2} + C$$

$$-\frac{1}{y} = -\frac{1}{2} \frac{1}{t^2} + C$$

$$\frac{1}{y} = \frac{1}{2t^2} - C$$

$$y = \frac{1}{\frac{1}{2t^2} - C} \cdot \frac{2t^2}{2t^2} = \frac{2t^2}{1 - 2ct^2}$$

first order
differential eqn.
not linear
separable

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$$c) \quad (2yt-1)y' = (t+1)e^t - y^2$$

$$(y^2 - (t+1)e^t) + (2yt-1)y' = 0$$

$$h'_t = y^2 - (t+1)e^t$$

$$h'_y = 2yt-1$$

Exact?

$$\frac{\partial h}{\partial t} + \frac{\partial h}{\partial y} \cdot y' = 0$$

Solution:

$$h(y,t) = C$$

$$h = y^2 t - y + C(t)$$

$$h'_t = y^2 + C'(t) = y^2 - (t+1)e^t$$

$$C'(t) = -(t+1)e^t$$

$$C(t) = \int -(t+1)e^t dt$$

$u = -(t+1)$	$v = e^t$
$u' = -1$	$v' = e^t$

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$$= \int uv' dt = uv - \int u'v dt$$

$$= -(t+1)e^t - \int (-1)e^t dt$$

$$= -(t+1)e^t + e^t + C$$

$$= (-t-1+1)e^t + C = -te^t + C$$

$$h = \underline{y^2 t - y - te^t}$$

Solution: $y^2 t - y - te^t = K$

$$(t)y^2 - 1 \cdot y + (-te^t - K) = 0$$

$$y = \frac{1 \pm \sqrt{1 - 4t(-te^t - K)}}{2t}$$

$$= \frac{1 \pm \sqrt{1 + 4t(te^t + K)}}{2t}$$

B) Constrained optimization

Lagrange problem:

Optimization, Equality constraints

$$\max / \min f(x_1, \dots, x_n) \quad \text{when} \quad \begin{cases} g_1(x_1, \dots, x_n) = a_1 \\ g_2(x_1, \dots, x_n) = a_2 \\ \vdots \\ g_m(x_1, \dots, x_n) = a_m \end{cases}$$

$$L = f(\underline{x}) - \lambda_1 \cdot g_1(\underline{x}) - \lambda_2 \cdot g_2(\underline{x}) - \dots - \lambda_m \cdot g_m(\underline{x})$$

FOC:

$$\begin{aligned} \frac{\partial L}{\partial x_1} &= 0 \\ \frac{\partial L}{\partial x_2} &= 0 \\ &\vdots \\ \frac{\partial L}{\partial x_n} &= 0 \end{aligned}$$

C:

$$\begin{aligned} g_1(\underline{x}) &= a_1 \\ &\vdots \\ g_m(\underline{x}) &= a_m \end{aligned}$$

FOC + C = Lagrange conditions

Solutions of Lagrange condition \Rightarrow Candidates for max/min.

Kuhn-Tucker problem:

Optimization, closed inequality constraints (\leq)

$$\max f(x_1, \dots, x_n) \quad \text{when} \quad \begin{cases} g_1(\underline{x}) \leq a_1 \\ g_2(\underline{x}) \leq a_2 \\ \vdots \\ g_m(\underline{x}) \leq a_m \end{cases}$$

Standard form: $\max \leq a_i$

$$L = f(\underline{x}) - \lambda_1 g_1(\underline{x}) - \dots - \lambda_m g_m(\underline{x})$$

FOC:

$$\begin{aligned} \frac{\partial L}{\partial x_1} &= 0 \\ \frac{\partial L}{\partial x_2} &= 0 \\ &\vdots \\ \frac{\partial L}{\partial x_n} &= 0 \end{aligned}$$

C:

$$\begin{aligned} g_1(\underline{x}) &\leq a_1 \\ &\vdots \\ g_m(\underline{x}) &\leq a_m \end{aligned}$$

CSC:

FOC + C + CSC = Kuhn-Tucker conditions

Foc: $L'_{x_1} = 0$
 \vdots
 $L'_{x_n} = 0$

C: $g_1(x) \leq a_1$
 $g_2(x) \leq a_2$
 \vdots
 $g_m(x) \leq a_m$

CSC: $\lambda_1 \geq 0$ and $\lambda_1 (g_1(x) - a_1) = 0$
 $\lambda_2 \geq 0$ " $\lambda_2 (g_2(x) - a_2) = 0$
 \vdots
 $\lambda_m \geq 0$ " $\lambda_m (g_m(x) - a_m) = 0$

Solutions of Kuhn-Tucker conditions \Rightarrow candidates for max

Note:

$g_i(x) \leq a_i$, $\lambda_i \geq 0$ and $\lambda_i (g_i(x) - a_i) = 0$

or be written:

(binding)	(non-binding)
$g_i(x) = a_i$	$g_i(x) < a_i$
$\lambda_i \geq 0$	$\lambda_i = 0$

Methods to conclude

i) Second order conditions (SOC)

If $(x^*; \lambda^*)$ is a candidate point that satisfies KKT-conditions, then

- | | | |
|------------------------|---------------------------------|---------------------------------|
| * $H(L(x; \lambda^*))$ | neg. semidefn. for all x | ($L(x; \lambda^*)$ is concave) |
| | $\Rightarrow x^*$ is <u>max</u> | |
| * $H(L(x; \lambda^*))$ | pos. semidefn. for all x | ($L(x; \lambda^*)$ is convex) |
| | $\Rightarrow x^*$ is <u>min</u> | |

ii) Extreme Value thm + Exhaustion.

Extreme Value thm (EVT):

If the set of adm. pts (points that satisfy all constraints) is bounded, then there is a max and a min.

Exhaustion: Check all possibilities

- i) All regular candidates, i.e. solutions to the KKT-conditions.
- ii) All adm. points that fails NDCQ.

NDCQ:

$$\text{rk} \begin{pmatrix} g'_{x_1} & g'_{x_2} & \dots & g'_{x_n} \end{pmatrix} = 1$$

$$g(x) < a$$

no condition

Question 4.

max $f = x + 4y + 2z + 5w$ when $2x^2 + 2y^2 + 2z^2 + 2w^2 + 2yz \leq 21$

Std form.

a) $L = x + 4y + 2z + 5w - \lambda \cdot (2x^2 + 2y^2 + 2z^2 + 2w^2 + 2yz)$

FOC:

$$L'_x = 1 - \lambda \cdot 4x = 0$$

$$L'_y = 4 - \lambda \cdot (4y + 2z) = 0$$

$$L'_z = 2 - \lambda \cdot (2y + 4z) = 0$$

$$L'_w = 5 - \lambda \cdot 4w = 0$$

C + CSC:

$$2x^2 + 2y^2 + 2z^2 + 2w^2 + 2yz = 21$$

a) $\lambda \geq 0$

or

$$2x^2 + 2y^2 + 2z^2 + 2w^2 + 2yz < 21$$

b) $\lambda = 0$

Case b): $\lambda = 0$ impossible (because of FOC's)
 \Rightarrow no candidates

Case a):

FOC: $1 - \lambda \cdot 4x = 0$

$$5 = 4\lambda \cdot w$$

$$4\lambda x = 1$$

$$w = \frac{5}{4\lambda}$$

$$x = \frac{1}{4\lambda}$$

$$4 = \lambda \cdot (4y + 2z)$$

$$2 = \lambda \cdot (2y + 4z)$$

$$0 = \lambda \cdot (0 - 6z)$$

$$0 = -6\lambda z$$

~~$\lambda = 0$~~ or $z = 0$

$$4 = \lambda \cdot (4y)$$

$$y = \frac{4}{4\lambda}$$

Foc:

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$$x = \frac{1}{4\lambda} \quad y = \frac{4}{4\lambda} \quad z = 0 \quad w = \frac{5}{4\lambda}$$

$$2x^2 + 2y^2 + 2yz + 2z^2 + 2w^2 = 21, \quad \lambda \geq 0$$

$$2 \cdot \left(\frac{1}{4\lambda}\right)^2 + 2 \cdot \left(\frac{4}{4\lambda}\right)^2 + 2 \cdot \left(\frac{5}{4\lambda}\right)^2 = 21$$

$$\frac{2 + 32 + 50}{(4\lambda)^2} = 21$$

$$\frac{84}{(4\lambda)^2} = 21$$

$$\frac{84}{21} = (4\lambda)^2$$

$$(4\lambda)^2 = 4$$

$$4\lambda = \pm 2$$

$$\lambda = \pm \frac{2}{4} = \pm \frac{1}{2}$$

$$x = \frac{1}{2}, \quad y = 2, \quad z = 0, \quad w = \frac{5}{2}, \quad \lambda = \frac{1}{2}$$

One regular candidate pt: $(x, y, z, w, \lambda) = \left(\frac{1}{2}, 2, 0, \frac{5}{2}; \frac{1}{2}\right)$

$$b) \quad f\left(\frac{1}{2}, 2, 0, \frac{5}{2}\right) = \frac{1}{2} + 4 \cdot 2 + 2 \cdot 0 + 5 \cdot \frac{5}{2} = 8 + \frac{25}{2} = \underline{\underline{21}}$$

SOC: $L(x, y, z, w; \frac{1}{2}) = x + 4y + 2z + 5w - \frac{1}{2}(2x^2 + 2y^2 + 2yz + 2z^2 + 2w^2)$

$$H(L) = \begin{pmatrix} -2 & 0 & 0 & 0 & 0 \\ 0 & -2 & -1 & 0 & 0 \\ 0 & -1 & -2 & 0 & 0 \\ 0 & 0 & 0 & -2 & 0 \end{pmatrix}$$

neg. semidef.?

$$\begin{array}{l}
 D_1 = -2 < 0 \\
 D_2 = 4 > 0 \\
 D_3 = -2 \cdot (4-1) = -6 < 0 \\
 D_4 = -2 \cdot D_3 = 12 > 0
 \end{array}
 \left. \vphantom{\begin{array}{l} D_1 \\ D_2 \\ D_3 \\ D_4 \end{array}} \right\} \begin{array}{l} \text{neg. defn.} \\ \parallel \\ \text{neg. semidef.} \\ \parallel \\ h(x, y, z, w; 1/2) \text{ concave} \\ \parallel \\ (1/2, 2, 0, 5/2) \text{ is } \underline{\underline{\text{max}}} \\ \text{by the SOC, with} \\ \text{max value } \underline{\underline{21}} \end{array}$$

c) $\max x + \underline{3.8}y + 2z + \underline{5.4}w$ when \dots
(as before)

KT-problem with parameters:

$$\max x + ay + 2z + bw \quad \text{wh} \quad 2x^2 + 2y^2 + 2yz + 2z^2 + 2w^2 \leq 21$$

$f^*(a, b)$: max value when the parameters are a, b

We know: $f^*(4, 5) = 21$

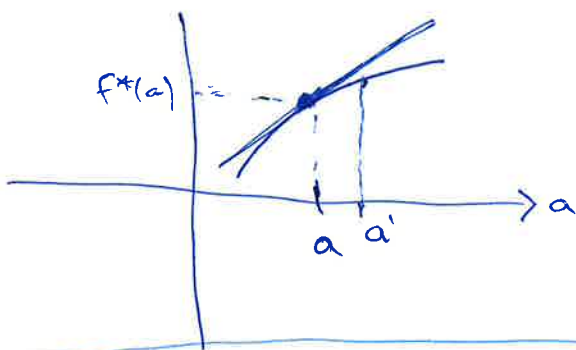
We want to estimate: $f^*(3.8, 5.4) = ?$

Linear approx: $f^*(3.8, 5.4) \approx f^*(4, 5) + \Delta a \cdot \frac{df^*}{da} + \Delta b \cdot \frac{df^*}{db}$

$$= \underline{\underline{21 - 0.2 \cdot \frac{df^*}{da} + 0.4 \cdot \frac{df^*}{db}}}$$

Envelope Thm.!





$$f^*(a') \approx f^*(a) + \Delta a \cdot \frac{\partial f^*}{\partial a}$$

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Envelope Thm: $\frac{df^*(a)}{da} = \frac{\partial L}{\partial a} \Big|_{\underline{x} = \underline{x}^*(a), \underline{\lambda} = \underline{\lambda}^*(a)}$

$$L = x + ay + 2z + bw - \lambda \cdot (2x^2 + 2y^2 + 2yz + 2z^2 + w^2 - 2)$$

$$\frac{\partial L}{\partial a} = y$$

$$\frac{\partial L}{\partial b} = w$$

Env. Thm:

$$\frac{\partial f^*(a,b)}{\partial a} = y^*(a,b)$$

$$\frac{\partial f^*(a,b)}{\partial b} = w^*(a,b)$$

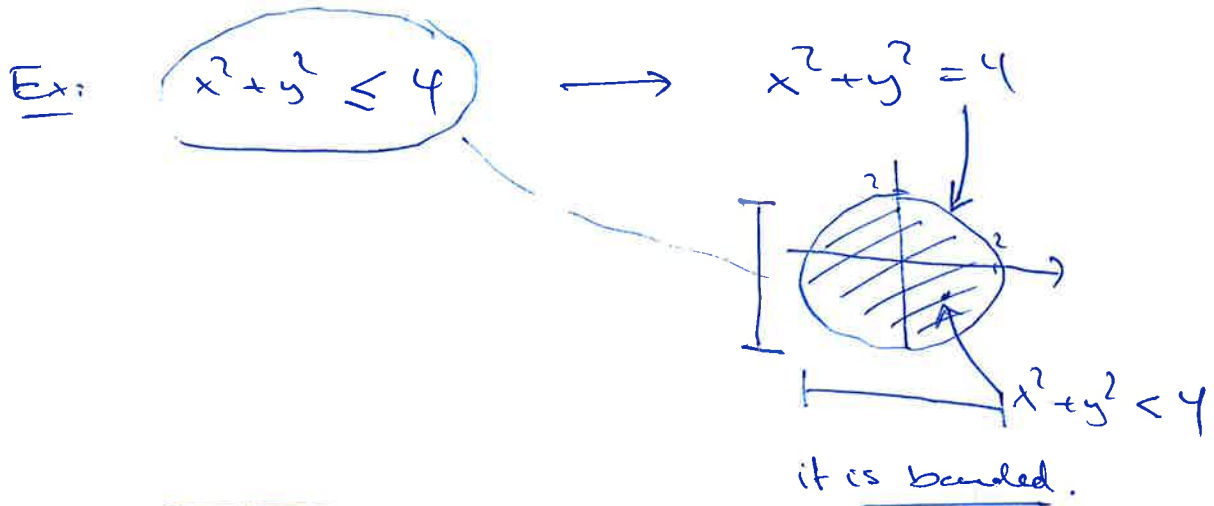
\Downarrow

$$f^*(3.6, 5.4) \approx f^*(4, 5) + 0.2 \cdot \overset{y^*(4,5)}{\downarrow} 2 + 0.4 \cdot \overset{w^*(4,5)}{\downarrow} \frac{5}{2}$$

$$= 2 - 0.4 + 1 = \underline{\underline{2.6}}$$

How to check that a set is bounded?

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Question:

is there a smallest and largest value of x among adu. pts.?

is there a smallest and largest value of y among adu pts.?